

# Matrix and Tensor Factorization from a Machine Learning Perspective

Christoph Freudenthaler

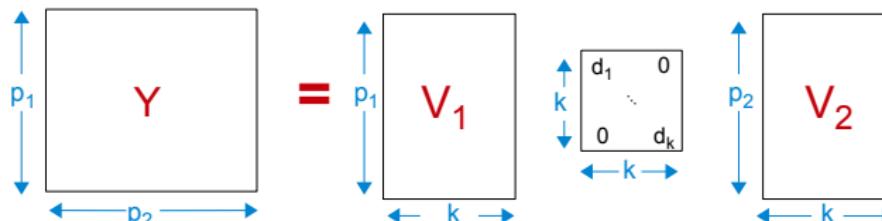
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Research Seminar, Vienna University of Economics and Business, January 13, 2012



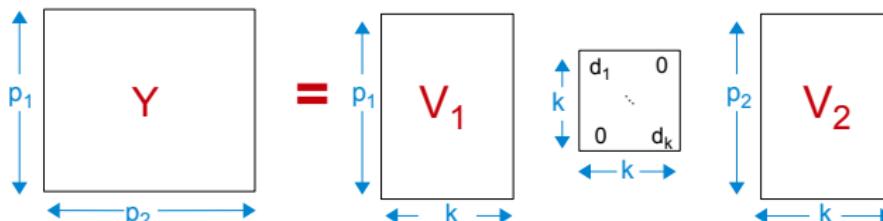
# Matrix Factorization - SVD

- **SVD:** Decompose  $p_1 \times p_2$  matrix  $Y := V_1 D V_2^T$ 
  - $V_1$  are  $k$  eigenvectors of  $YY^T$
  - $V_2$  are  $k$  eigenvectors of  $Y^T Y$
  - $D := \sqrt{\text{eig}(\text{diag}(YY^T))}$



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## Properties:

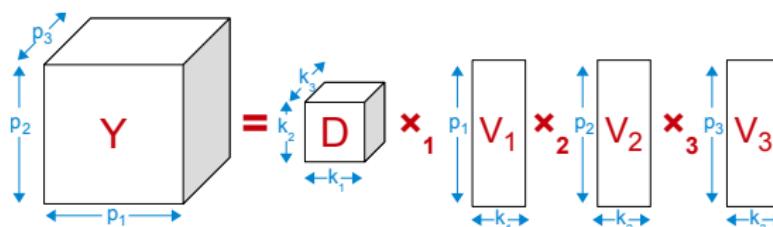
- Method from linear algebra for arbitrary  $Y$
- Tool for descriptive and exploratory data analysis
- Decomposition optimizes the Frobenius norm with orthogonality constraints

# Tensor Factorization - Tucker Decomposition

## ► Tucker Decomposition:

Decompose  $p_1 \times p_2 \times p_3$  tensor  $Y := D \times_1 V_1 \times_2 V_2 \times_3 V_3$

- $V_1$  are  $k_1$  eigenvectors of mode-1 unfolded  $Y$
- $V_2$  are  $k_2$  eigenvectors of mode-2 unfolded  $Y$
- $V_3$  are  $k_3$  eigenvectors of mode-3 unfolded  $Y$
- $D \in \mathbb{R}^{k_1 \times k_2 \times k_3}$  non-diagonal core tensor

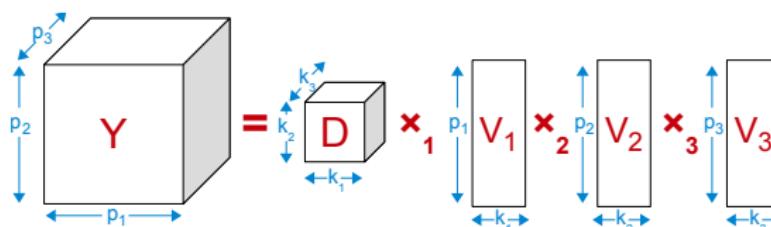


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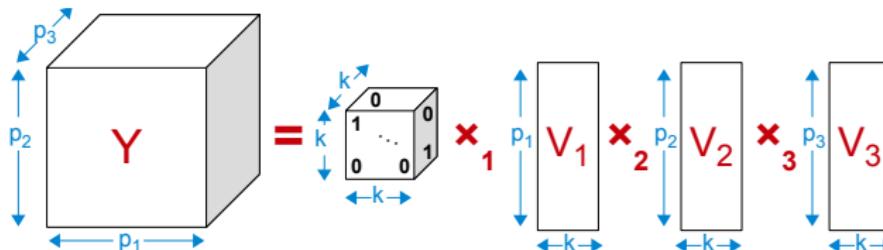
- Extension of SVD method for arbitrary tensor  $Y \rightarrow$  orthogonal representation
- Tool for descriptive and exploratory data analysis
- Decomposition optimizes the Frobenius norm
- Expensive inference: sequences of SVD + core tensor  $D$

# Tensor Factorization - Canonical Decomposition

## ► Canonical Decomposition (CD):

Decompose  $p_1 \times p_2 \times p_3$  tensor  $Y := D \times_1 V_1 \times_2 V_2 \times_3 V_3$

- ▶ with diagonal, identity tensor  $D$
- ▶ as a sum of  $k$  rank-one tensors  $Y = \sum_{f=1}^k \mathbf{v}_{1,f} \circ \mathbf{v}_{2,f} \circ \mathbf{v}_{3,f}$

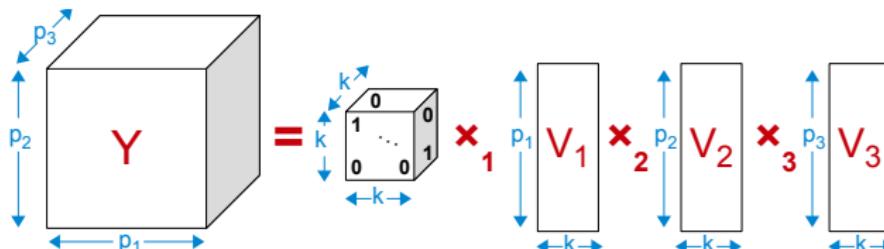


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## Properties:

- ▶ Extension of SVD method for arbitrary tensor  $Y$
- ▶ Tool for descriptive and exploratory data analysis
- ▶ Decomposition optimizes the Frobenius norm
- ▶ Fast inference due to less parameters

# Machine Learning Perspective

## Machine Learning:

...is the task of

- ▶ learning from (noisy) experience **E** with respect to some class of tasks **T** and performance measure **P**
  - ▶ Experience **E**: data
  - ▶ Tasks **T**: predictions
  - ▶ Performance **P**: root mean square error (RMSE), misclassification,...

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In other words:

- ▶ **Prediction accuracy on new cases** = Machine Learning
- ▶ **No hypothesis generation/testing** = Data Mining

# Applications of the Machine Learning Perspective

**Many different applications:**

- ▶ Social Network Analysis
- ▶ Recommender Systems
- ▶ Graph Analysis
- ▶ Image/Video Analysis
- ▶ ...



# Applications of the Machine Learning Perspective

## Overall Task:

- ▶ **Prediction** of missing friendships, interesting items, corrupted pixels, missing edges, etc.
- ▶ **Data representation:** matrix/tensor with missing entries

$$\mathbf{Y} = \begin{array}{c|ccccc} & i_1 & i_2 & i_3 & \dots & i_{p_2-1} & i_{p_2} \\ \hline u_1 & 3 & & & & & 5 \\ u_2 & 3 & 4 & 4 & & & \\ \vdots & & & & & & \\ u_{p_1} & & 5 & & 2 & & 2 \end{array}$$

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### **Further Properties:**

- ▶ **Unobserved Heterogeneity**, e.g. different consumption preferences of different users and items → Factorization Models
  - ▶ **Large-scale**: millions of interactions
  - ▶ **Poor Data Quality**: high noise due to indirect data collection

# Factorization Models from a Machine Learning Perspective

## Common usage of matrix (and tensor) factorization:

- ▶ Identification/Interpretation of unobserved heterogeneity, i.e. latent dependencies between instances of a mode (rows, columns, . . . )
- ▶ Data compression, e.g., instead of  $p_1 p_2$  values, store only  $(p_1 + p_2)k$  values
- ▶ Data preprocessing: uncorrelate  $p$  predictor variables of a design matrix  $X$

# Factorization Models from a Machine Learning Perspective

## Machine Learning perspective on factorization models:

- ▶ Factorization models seen as predictive models
  - ▶ No probabilistic embedding, e.g. for Bayesian Analysis
  - ▶ Gaussian likelihood:

$$Y = V_1 D V_2^T + E, \quad \forall e_\ell \in E : e_\ell \sim N(0, \sigma^2 = 1)$$

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  - ▶ Elimination of orthonormality constraint  $Y = V_1, V_2^T + E$
  - ▶ → for general tensors:

$$Y = \sum_{f=1}^k \mathbf{v}_{1,f} \circ \mathbf{v}_{2,f} \circ \dots \circ \mathbf{v}_{m,f} + E$$

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# Related Work

## Existing Extensions of Factorization Models:

- ▶ More general likelihood for multinomial, count data, etc.  
→ Exponential Family PCA<sup>1</sup>
- ▶ Inference only on observed tensor entries

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## Missing Extensions:

- ▶ Extensions of the predictive models, i.e. SVD, CD
- ▶ Comparison to standard predictive models

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# Outline

Generalized Factorization Model

Relations to standard Models

Empirical Evaluation

Conclusion and Discussion

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## Generalized Factorization Model

Relations to standard Models

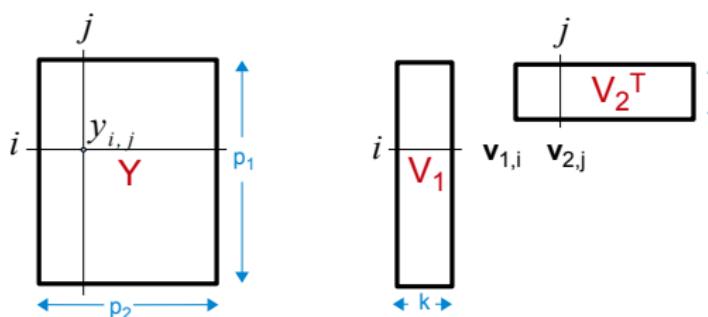
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Conclusion and Discussion

# Probabilistic SVD

**Frobenius norm optimal:**

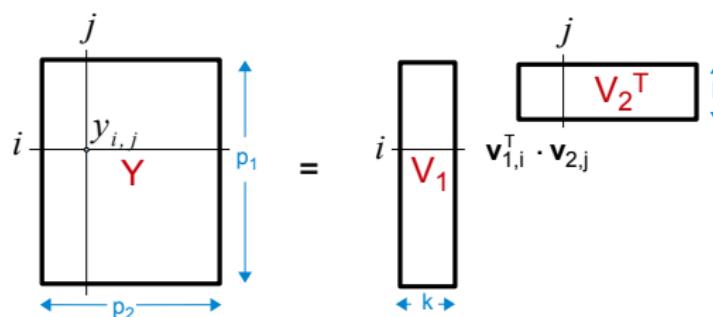
$$\underset{\theta=\{V_1, V_2\}}{\operatorname{argmin}} \|Y - V_1 V_2^T\|_F = \sum_{i=1}^{p_1} \sum_{j=1}^{p_2} (y_{i,j} - \mathbf{v}_{1,i}^T \mathbf{v}_{2,j})^2$$



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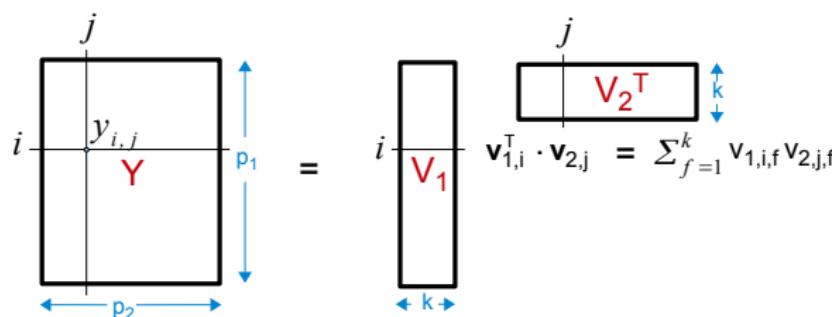
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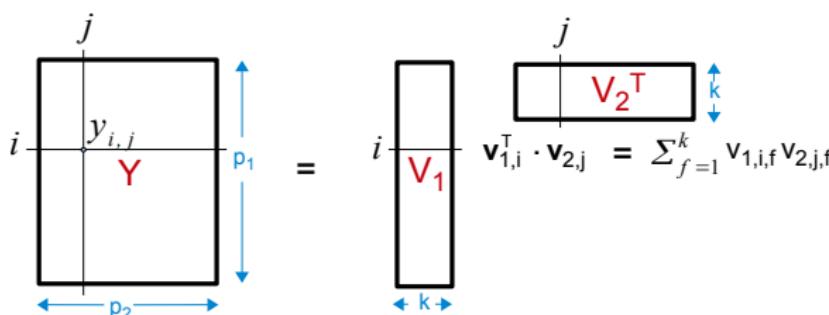
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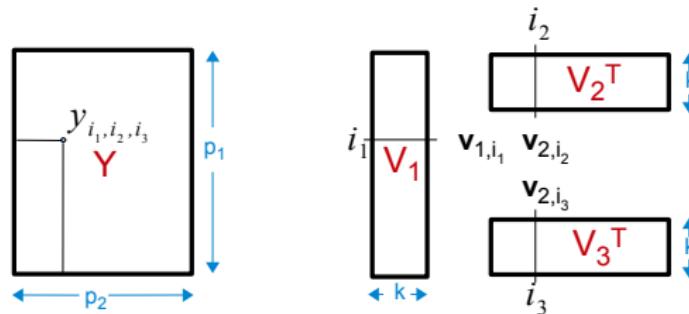
$\propto$  Gaussian maximum likelihood:

$$\operatorname{argmax}_{\theta=\{V_1, V_2\}} \prod_{i=1}^{p_1} \prod_{j=1}^{p_2} \exp \left( -\frac{1}{2} (y_{i,j} - \mathbf{v}_{1,i}^T \mathbf{v}_{2,j})^2 \right)$$

# Probabilistic CD - Extend SVD to arbitrary $m$

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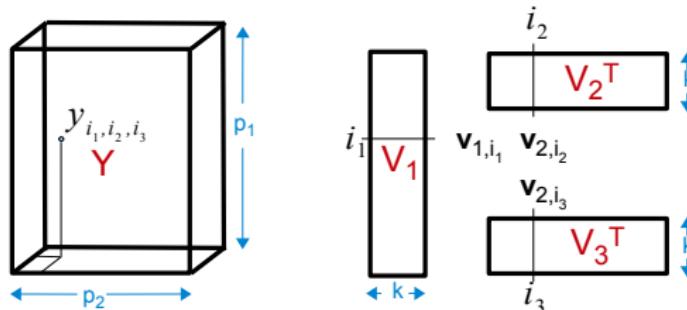
$$\operatorname{argmin}_{\theta = \{V_1, V_2, \dots, V_m\}} \sum_{i_1=1}^{p_1} \sum_{i_2=1}^{p_2} \dots \sum_{i_m=1}^{p_m} (y_{i_1, i_2, \dots, i_m} - \underbrace{\sum_{f=1}^k v_{1,i_1,f} v_{2,i_2,f} \dots v_{m,i_m,f}}_{y_{i_1, i_2, \dots, i_m}^{CD}})^2$$



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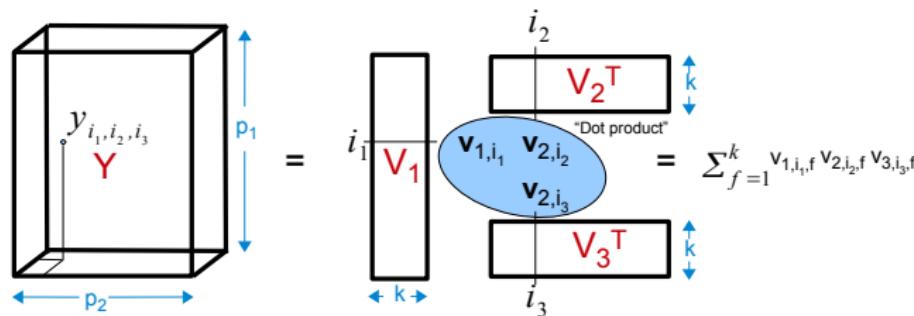
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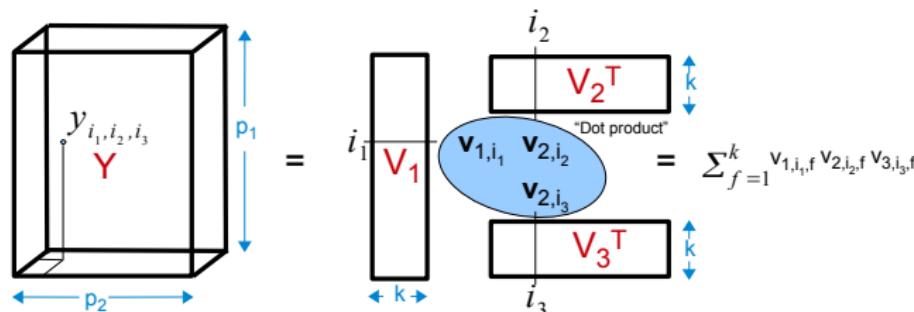
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# GFM I: Predictive Model Interpretation

## Adapt Notation:

- ▶ Introduce for each tensor element  $\ell = 1, \dots, n$  vector-valued indicator vectors  $\mathbf{x}_{\ell,j}$ ,  $j = 1, \dots, m$  of length  $p_j$

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- ▶ Form for each tensor element  $y_{i_1, \dots, i_m}$  a predictor vector  $\mathbf{x}_\ell \in \mathbb{R}^{p=p_1+p_2+\dots+p_m}$  by concatenating  $\mathbf{x}_j$ :

$$\mathbf{x}_\ell^{CD} = \left( \underbrace{0, \dots, 1, \dots, 0}_{\mathbf{x}_{\ell,1}}, \underbrace{0, \dots, 1, \dots, 0}_{\mathbf{x}_{\ell,2}}, \dots \right)$$

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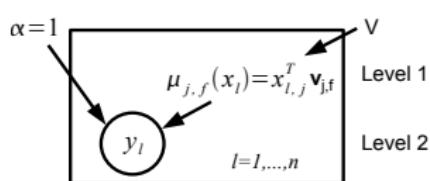
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- ▶ Rewrite  $y_{i_1, \dots, i_m}^{CD}$  as  $y_{i_1, \dots, i_m}^{CD} = y_\ell^{CD} = f(x_\ell^{CD} | V)$
- ▶ with general  
$$f(x_\ell | V) = \sum_{f=1}^k \prod_{j=1}^m \mathbf{x}_{\ell,j}^T \mathbf{v}_{j,f} = \sum_{f=1}^k v_{1,i_1,f} v_{2,i_2,f} \dots v_{m,i_m,f}$$

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**More intuitive interpretation:** 2-level hierarchical representation

$$y_\ell \sim N(\mu_\ell, \alpha = 1)$$

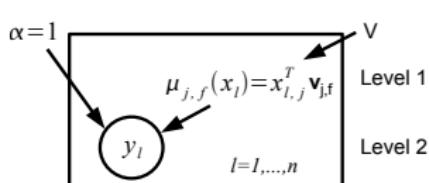


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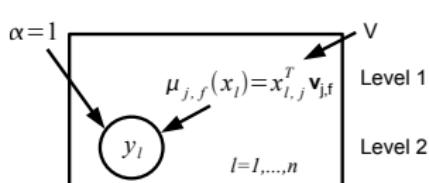
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- ▶ each pair of mode  $j$  and latent dimension  $f$  has a different linear model  $\mu_{j,f}(\mathbf{x}_\ell) = \mathbf{x}_{\ell,j}^T \mathbf{v}_{j,f}$
- ▶ with predictor vector  $\mathbf{x}_{\ell,j}$  describing each mode  $j$  and  $p_j$  different model parameters  $\mathbf{v}_{j,f}$  per mode  $j$  and latent dimension  $f$

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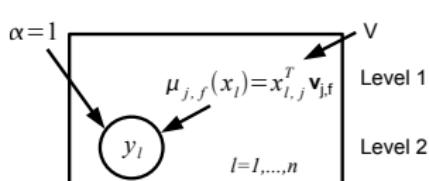
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- ▶ → factorization models are 2-level hierarchical (multi-)linear models with
  - ▶  $\mu_{j,f}(\mathbf{x}_\ell)$  per latent dimension  $f$  and mode  $j$  in the upper level

# GFM I: Predictive Model Interpretation

**More intuitive interpretation:** 2-level hierarchical representation

$$y_\ell \sim N(\mu_\ell, \alpha = 1)$$



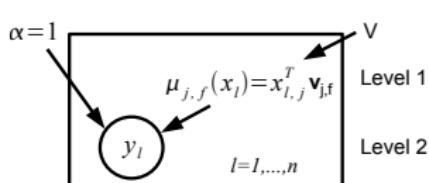
$$f(\mathbf{x}_\ell | V) = \mu_\ell = \sum_{f=1}^k \prod_{j=1}^m \underbrace{\mathbf{x}_{\ell,j}^T \mathbf{v}_{j,f}}_{\mu_{j,f}(\mathbf{x}_\ell)}$$

- ▶ each pair of mode  $j$  and latent dimension  $f$  has a different linear model  $\mu_{j,f}(\mathbf{x}_\ell) = \mathbf{x}_{\ell,j}^T \mathbf{v}_{j,f}$
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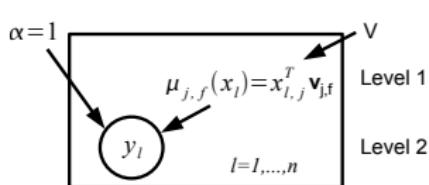
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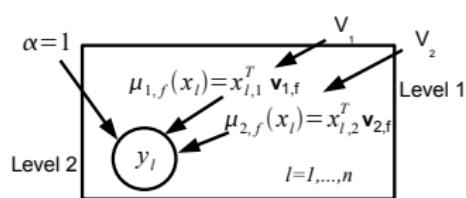
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  - ▶ and  $y_\ell^{CD} = f(\mathbf{x}_\ell^{CD} | V)$  using  $\mathbf{x}_\ell^{CD}$

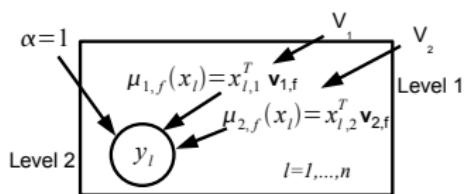
# Important example: Matrix Factorization



Level 1:

- ▶  $\mu_{1,f}(\mathbf{x}_\ell) = \mathbf{x}_{\ell,1}^T \mathbf{v}_{1,f}$  ( $k$  row means)
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Level 2:

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# GFM II: Predictive Model Extension

**From  $x_\ell^{CD}$  to arbitrary  $x_\ell$ :**

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- ▶ Mode-vectors  $\mathbf{x}_{\ell,j}$  may be defined arbitrarily, e.g., to take into account more complex conditional dependencies

# Understanding induced dependencies:

**Overall independence assumption:**  $y_\ell | \mathbf{x}_\ell \sim N(\mu_\ell = f(\mathbf{x}_\ell | V), 1)$

- **Simplest case SVD:** Correlation only on identical mode-indices, e.g. row or column index  $\leftrightarrow$  rows/columns are independent from other rows/columns

$$\begin{matrix} & j \\ & \downarrow \\ \begin{matrix} & j \\ i & \text{---} \\ & \downarrow \\ \boxed{y_{i,j}} \\ & \uparrow \\ \text{Y} \end{matrix} & \end{matrix} = \begin{matrix} & j \\ & \downarrow \\ \begin{matrix} & j \\ i & \text{---} \\ & \downarrow \\ \boxed{\mathbf{V}_1^T} \\ & \uparrow \\ \mathbf{V}_1 \end{matrix} & \end{matrix} \cdot \begin{matrix} & j \\ & \downarrow \\ \boxed{\mathbf{V}_2^T} \\ & \uparrow \\ \mathbf{V}_2 \end{matrix} = \sum_{f=1}^k \mathbf{v}_{1,i,f} \mathbf{v}_{2,j,f}$$

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$$\begin{array}{c|cc}
 j & & \\
 \hline
 i & y_{i,j} & \\
 \hline
 & p_1 & \\
 & \textcolor{red}{Y} & \\
 & p_2 & \\
 \hline
 \end{array} = \begin{array}{c|cc}
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 \hline
 i & \mathbf{V}_1 & \\
 \hline
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- e.g.  $p_1 = 3$  rows,  $p_2 = 8$  columns:

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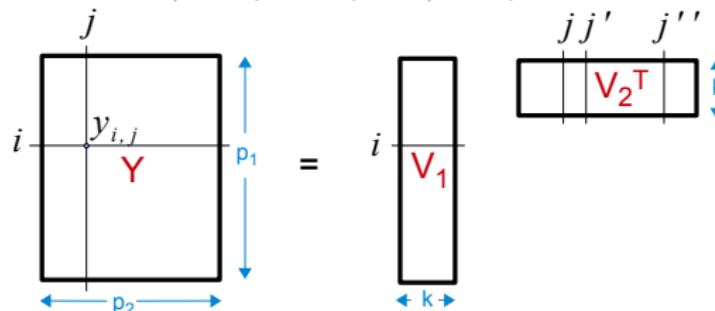
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<sup>4</sup>Koren, Y.: Factorization meets the neighborhood: a multifaceted collaborative filtering model, KDD08.

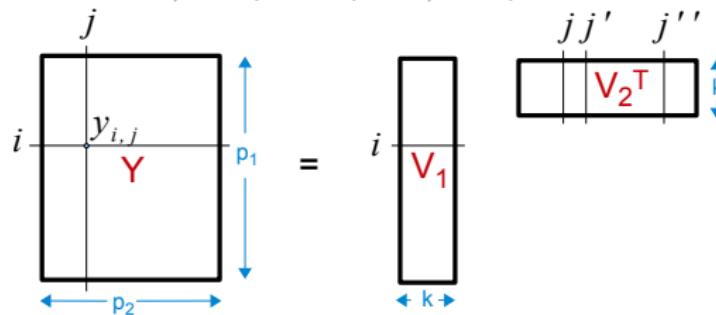
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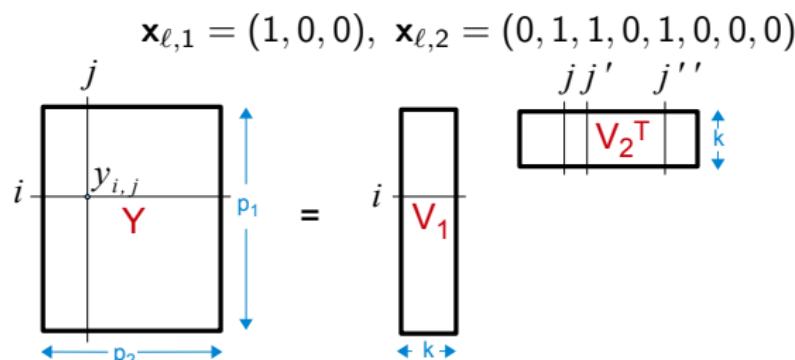
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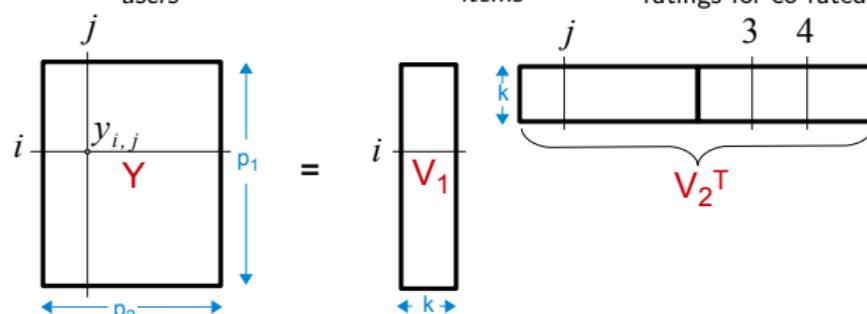
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$p_1 = 3$  rows and  $p_2 = 8$  columns + additional rating information:

$$\mathbf{x}_{\ell,1} = (\underbrace{1, 0, 0}_{\text{users}}, \underbrace{0, 1, 0, 0, 0, 0, 0, 0}_{\text{items}}, \underbrace{0, 0, 3, 0, 4, 0, 0, 0}_{\text{ratings for co-rated items}})$$



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5

Rendle, S., Freudenthaler, C., Schmidt-Thieme, L.: Factorizing personalized Markov chains for next-basket

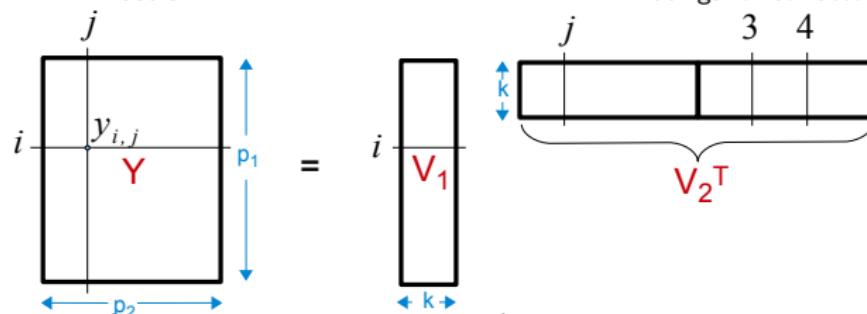
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► Example from recommender systems: Factorized Transition Tensors<sup>5</sup>

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# GFM II: Predictive Model Extension II

$$f(\mathbf{x}_\ell | V) = \mu_\ell = \sum_{f=1}^k \prod_{j=1}^m \mathbf{x}_{\ell,j}^T \mathbf{v}_{j,f} = \sum_{f=1}^k \prod_{j=1}^m \sum_{i_j=1}^{p_j} x_{\ell,j,i_j} v_{j,i_j,f}$$

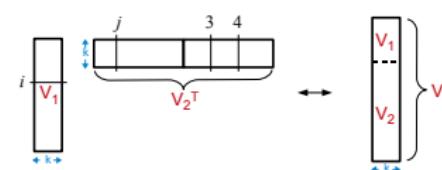
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- ▶ Only one predictive model per mode  $m$
- ▶ Increase predictive accuracy: combine several reasonable predictive models per mode
- ▶ Introduce mode-defining selection vectors  $\mathbf{d}_j \in \{0, 1\}^p$  on  $\mathbf{x}_\ell = (\mathbf{x}_1, \dots, \mathbf{x}_m) \in \mathbb{R}^p$ ,  $j = 1, \dots, m$
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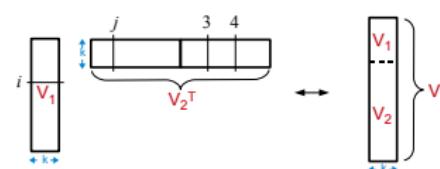
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- ▶ Collect several selection sets  $\{\mathbf{d}_1, \dots, \mathbf{d}_m\} \in \mathcal{D}$ :

$$f^{GFM}(\mathbf{x}_\ell | V) = \mu_\ell = \sum_{f=1}^k \sum_{\{\mathbf{d}_1, \dots, \mathbf{d}_m\} \in \mathcal{D}} \prod_{j=1}^m \sum_{i=1}^{p_j} x_{\ell,i} \mathbf{d}_{j,i} \mathbf{v}_{i,f}$$

# GFM II: Predictive Model Learning?

$$f^{GFM}(\mathbf{x}_\ell | V) = \sum_{i_1=1}^p \cdots \sum_{i_m=1}^p x_{\ell, i_1} \cdots x_{\ell, i_m} \underbrace{\sum_{\mathcal{D}} d_{1, i_1} \cdots d_{m, i_m}}_{\text{Interaction Weight I}} \underbrace{\sum_{f=1}^k v_{i_1, f} \cdots v_{i_m, f}}_{\text{Interaction Weight II}}$$

- ▶ Infer model selection  $\mathcal{D} \rightarrow$  Bayesian model averaging ?
  - + Also negative interaction effects of even order
  - Redundant parameterization
  - Expensive model prediction  $O(|\mathcal{D}|kmp)$

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- ▶  $m = 2$  different modes,  $p$  different mode-models  $\rightarrow |\mathcal{D}| = mp = 2p$

$$\mathcal{D} = \left\{ \begin{array}{l} \{(d_{1,1}, \dots, d_{1,p}), \\ (d_{2,1}, \dots, d_{2,p})\} \end{array} : d_{1,i_1} = 1, d_{2,i_2} = 1 \ \forall i_2 > i_1, 0 \text{ else} \right\},$$

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- ▶ **ex.1:**  $\mathbf{d}_1 = (1, 0, 0, \dots, 0)$ ,  $\mathbf{d}_2 = (0, 1, 1, 1, \dots, 1)$

- ▶ **ex.2:**  $\mathbf{d}_1 = (0, 1, 0, \dots, 0)$ ,  $\mathbf{d}_2 = (0, 0, 1, 1, \dots, 1)$

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# Selecting a prior distribution:

**So far:**

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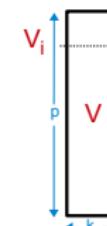
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→ **Conjugate Gaussian prior** distribution:

Each latent  $k$ -dim representation  $\mathbf{v}_i \in \mathbb{R}^k$ ,  
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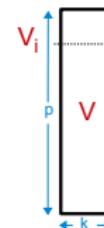


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→ **Conjugate Gaussian hyperprior:**

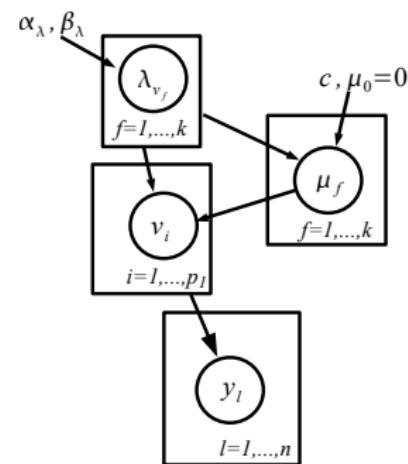
Each prior mean  $\mu_f$  is considered an independent realization of

$$\mu_f \sim N(\mu_0, \frac{c}{\lambda_f})$$

→ **Conjugate Gamma hyperprior:**

Each precision  $\lambda_f = \sigma_f^{-2}$  is considered an independent realization of

$$\lambda_f \sim G(\alpha_0, \beta_0)$$



# Learning Generalized Factorization Models

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- ▶ Learning on large datasets: block size = 1 →  $O(N_z k)$

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# Polynomial Regression

$$f(\mathbf{x}_\ell | V) = \sum_{i_1=1}^p x_{\ell,i_1} \beta_{i_1} + \sum_{i_1=1}^p \sum_{i_2 \geq i_1}^p x_{\ell,i_1} x_{\ell,i_2} \beta_{i_1, i_2} + \dots + \sum_{i_1=1}^p \dots \sum_{i_o \geq i_{o-1}}^p x_{\ell,i_1} \dots x_{\ell,i_o} \beta_{i_1, \dots, i_o}$$

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- ▶ Selecting  $\mathcal{D}$  accordingly gives

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# Polynomial Regression vs. GFM

## Generalized Factorization Model include Polynomial Regression

- ▶ For factorized parameters, e.g.  $\beta_{i_1, i_2} = \sum_{f=1}^k v_{i_1, f} v_{i_2, f}$
- ▶ If number of modes  $m$  equals order  $o$

# Factorization Machines<sup>6</sup> vs. GFM

- ▶ Very similar to previous factorized polynomial regression model

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<sup>6</sup>Rendle, S.: Factorization Machines. ICDM10.

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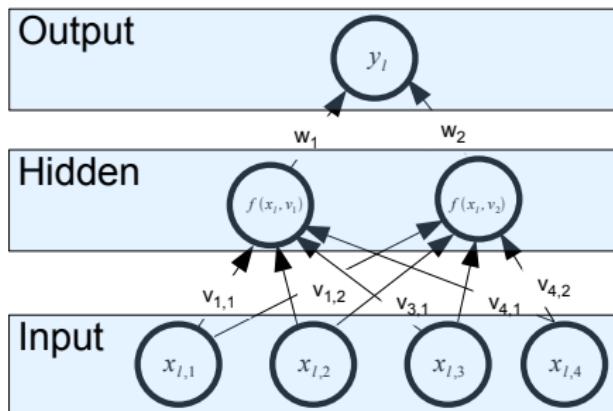
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- ▶ Factorization Machines using simple Gibbs are successfully applied in several challenges

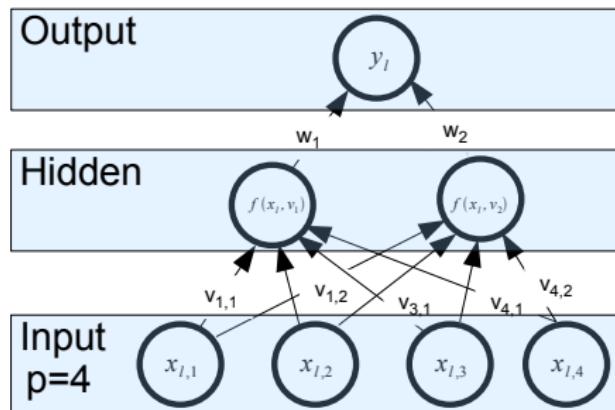
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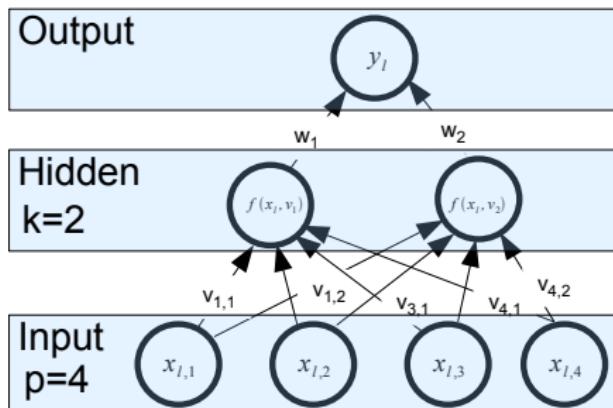


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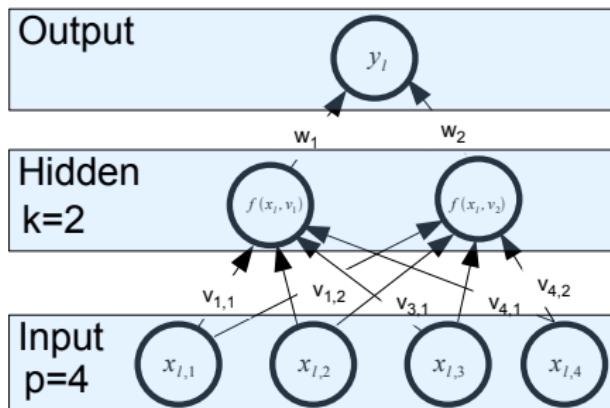
- **Input:** predictor vector  $\mathbf{x}_\ell \in \mathbb{R}^p$ ,  $\ell = 1, \dots, n$

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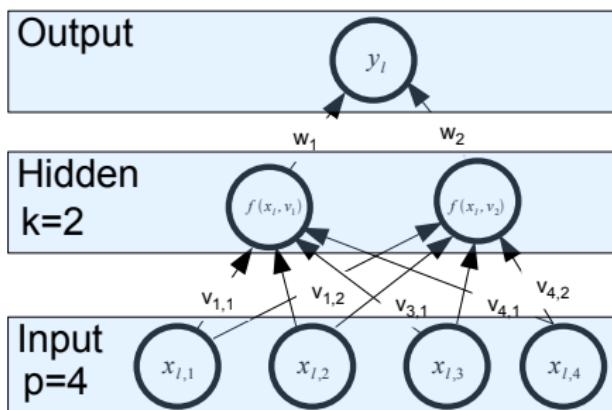
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- ▶ **Output:** Weights  $w_f = 1$

# Outline

Generalized Factorization Model

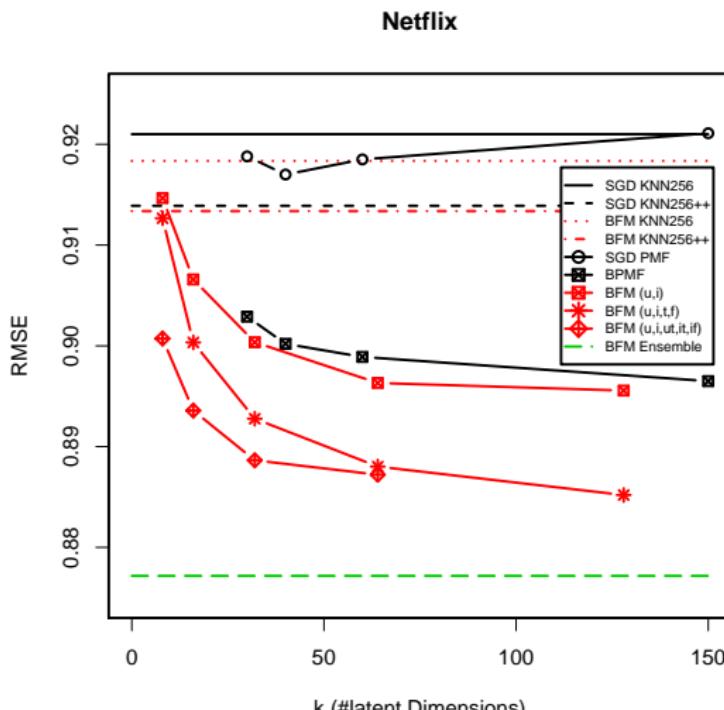
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# Empirical Evaluation on Recommender System Data

- ▶ **Task:** movie rating prediction
- ▶ **Data<sup>7</sup>:** 100M ratings of 480k users on 18k items



# Bayesian Factorization Machines - Kaggle

- ▶ **Task:** student performance prediction on GMAT (Graduate Management Admission Test), SAT and ACT (college admission test)
- ▶ **118 contestants**
- ▶ **Data<sup>8</sup>:**

#	Δ1w	Team Name	Capped Binomial Deviance	Entries	Last Submission UTC (Best Submission - Last)
1	-	Steffen *	0.24727	1	Sun, 04 Dec 2011 18:43:56
2	-	JP *	0.24773	9	Sun, 08 Jan 2012 23:56:28 (-3.1d)
3	-	YetiMan *	0.24795	22	Sat, 31 Dec 2011 16:56:22
4	-	PlanetThanet	0.24971	18	Tue, 10 Jan 2012 19:36:01
5	-	UCSD-Triton	0.25077	40	Mon, 09 Jan 2012 19:29:34 (-13.4d)

<sup>8</sup><http://www.kaggle.com/c/WhatDoYouKnow>

# Bayesian Factorization Machines - KDDCup'11

- ▶ **Task:** music rating prediction
- ▶ ≈ 1000 contestants
- ▶ **Data<sup>9</sup>:** 250M ratings of 1M users on 625k *items* (songs, tracks, album or artists)

Rank	Team Name	Best Score (RMSE)
1	National Taiwan University	21.0147
2	commando	21.0815
3	InnerPeace	21.2634
4	Aron	21.5721
5	LeBuSiShu	21.8637
6	ICTIRDreamer	22.1813
7	Frantisek Hrdina	22.3367
8	slp008	22.3968
9	Just a guy in a garage	22.4665
10	Try&Go	22.5924
11	UvAAI	22.8131
12	remainder	22.8803
13	yahookddkiddingme	22.8803
14	packy	22.8823
15	~語語語~語語語~語語語	22.8824
16	wahaha	22.8920
17	iloveZL	22.9125
18	libFM	22.9523
19	the_dl	22.9694
20	icad	23.0026

<sup>9</sup><http://kddcup.yahoo.com/>

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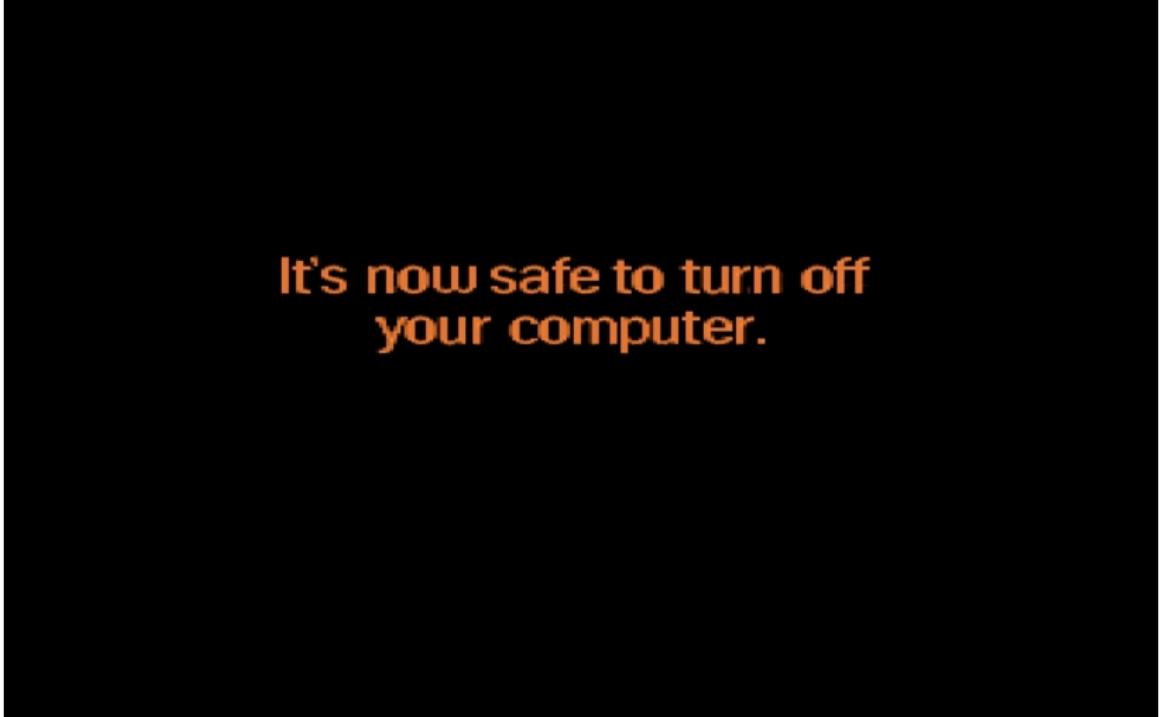
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## Open questions:

- ▶ Bayesian learning for models with non-linear functions of  $V$ ?
- ▶ Bayesian model averaging for GFM?
- ▶ Efficient Bayesian inference for non-Gaussian likelihood?



**It's now safe to turn off  
your computer.**