

Risk simulation with optimally stratified importance sampling

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Some Risk Measures

- Tail loss probability for given threshold level, τ :
$$\Pr(Loss \geq \tau) = E[\mathbb{1}\{Loss \geq \tau\}]$$
- $VaR(\alpha)$: Value-at-risk, $1 - \alpha$ quantile of the loss distribution.
- Conditional excess: $E[Loss|Loss \geq \tau]$
- Conditional value-at-risk: $CVaR(\alpha)$: $E[Loss|Loss \geq VaR(\alpha)]$

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t -copula for modeling log-returns

- For modeling dependence among log-returns the importance of copulae is stressed (Frey and McNeil, 2001).
- t -copula models have a good fit to the joint distribution of log returns. (for example Mashal et al. 2003; Krole et al. 2007).

$$\text{Return}(\mathbf{T}) = \sum_{d=1}^D w_d e^{c_d G_d^{-1}(F_\nu(T_d))}$$

$$c_d = \sqrt{\frac{\sigma_d^2}{252} \frac{1}{\text{var}_d}}$$

$$\mathbf{T} = (T_1, \dots, T_D)' = \frac{\mathbf{LZ}}{\sqrt{Y/\nu}}$$

Our Objectives

For a linear asset portfolio of moderate size (2 to 10 assets):

- Efficient estimation of a single tail loss probability, $\Pr(Loss \geq \tau)$
- Efficient estimation of a single conditional excess $E[Loss | Loss \geq \tau]$.
- Efficient estimation of multiple tail loss probabilities or multiple conditional excesses in a single simulation. (Important to calculate VaR and CVaR.)

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General Principles of Monte Carlo Simulation:

- Estimation of an expectation: $x = E_f [q(\mathbf{X})]$
 - $\mathbf{X} \in \mathbb{R}^D$ and \mathbf{X} has density $f(\cdot)$,
 - $q: \mathbb{R}^D \rightarrow \mathbb{R}$ is the "simulation function",
 - $E_f [q^2(\mathbf{X})] < \infty$.
- $x = E_f [q(\mathbf{X})] = \int_{\mathbf{x} \in \mathbb{R}^D} q(\mathbf{x}) f(\mathbf{x}) d\mathbf{x}$
- The naive estimator: $\hat{x}_{NV} = N^{-1} \sum_{n=1}^N q(\mathbf{X}^n)$
 - Generate iid sample $\mathbf{X}^1, \dots, \mathbf{X}^N$ from density $f(\cdot)$.
 - Central Limit Theorem: $\frac{\hat{x}_{NV} - x}{\sigma/N} \rightarrow N(0, 1)$.
 - Error bound: $\hat{x}_{NV} \pm \Phi^{-1}(\alpha/2) \sigma / \sqrt{N}$.
- To get more precise results: Variance Reduction Methods
 - Look for new simulation function $q(\cdot)$ with the same expectation and smaller variance

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Importance Sampling (IS)

IS is a frequently used method for rare event situations

- $$\begin{aligned} E_f[q(\mathbf{X})] &= \int_{\mathbf{x} \in \mathbb{R}^D} q(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} \\ &= \int_{\mathbf{x} \in \mathbb{R}^D} q(\mathbf{x}) \frac{f(\mathbf{x})}{f_{IS}(\mathbf{x})} f_{IS}(\mathbf{x}) d\mathbf{x} \\ &= \int_{\mathbf{x} \in \mathbb{R}^D} q(\mathbf{x}) \rho(\mathbf{x}) f_{IS}(\mathbf{x}) d\mathbf{x} \\ &= E_{f_{IS}}[q(\mathbf{X}) \rho(\mathbf{X})]. \end{aligned}$$

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- Regularity conditions are necessary to prove that the estimate is unbiased

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Importance Sampling cont.

- $V[\hat{x}_{IS}]$ is minimal for $f_{IS}^*(\mathbf{x}) = \frac{|q(\mathbf{x})| f(\mathbf{x})}{\int_{\mathbf{x} \in \mathbb{R}^D} |q(\mathbf{x})| f(\mathbf{x}) d\mathbf{x}}$

That density is unknown for relevant applications.

- In practice an IS density is typically taken from a parametric family (often the same as $f(\cdot)$). The parameters are selected such that the IS density imitates $|q(\mathbf{x}) f(\mathbf{x})|$.
- The cross entropy method is a general approach to select the parameters of the IS density.
- Often the variance reduction reached with IS decreases fast with the dimension of the problem.

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IS Algo for Tailloss Probabilities

Sak, WH and Leydold (2010) use IS for the iid normal input Z and the chi-square random variate Y .

- Problem: Even for heuristic approach necessary to find a good direction for Z . It depends on the threshold τ . Thus a numeric optimization is required.
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Stratified Sampling

- Let $\xi_i, i = 1, \dots, I$ be a partition of \mathbb{R}^D into I strata,
- Assume $p_i = \Pr \{ \mathbf{X} \in \xi_i \}$ are known for $i = 1, \dots, I$.
- Let \mathbf{X}_i be the random vector that follows the conditional distribution of \mathbf{X} given $\mathbf{X} \in \xi_i$.

$$x = E_f [q(\mathbf{X})] = \sum_{i=1}^I p_i E_f [q(\mathbf{X}) | \mathbf{X} \in \xi_i] = \sum_{i=1}^I p_i E_f [q(\mathbf{X}_i)]$$

- The stratified estimator: $\hat{x}_{STRS} = \sum_{i=1}^I p_i N_i^{-1} \sum_{n=1}^{N_i} q(\mathbf{X}_i^n)$
 - N_i replications in stratum i , $N = \sum_{i=1}^I N_i$
 - Generate iid sample $\mathbf{X}_i^1, \dots, \mathbf{X}_i^{N_i}$ in each stratum.
 - How should we select N_i , the sample size for each stratum?
 standard stratification uses proportional allocation
 possible generalisation to QMC

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- Define allocation fractions $\pi_i = N_i/N$

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1. Partition the domain of \mathbf{X} into l disjoint strata ξ_i .

2. Generate $\pi_i N$ iid random variables \mathbf{X}_i^n .

3. Compute the sample mean \hat{X}_{STRS} of $q(\mathbf{X}_i^n)$.

4. Use optimal allocation in the next run.

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Adaptive Optimal Allocation Algorithm

- The Adaptive Optimal Allocation (AOA) algorithm terminates in K iterations.
- The total sample size N is divided between iterations with a non-decreasing order (e.g., $K = 3, 0.1N, 0.4N, 0.5N$).
- In the first iteration, the sample is allocated proportional to stratum probabilities p_i .
 - In each iteration, the conditional standard deviations, σ_i , $i = 1, \dots, I$, are estimated using all previous drawings.
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Étoré and Jourdain (2010) show that the stratified estimator of AOA is unbiased and asymptotically normal.

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IS vs Optimal Allocation Stratification (OAS)

- OAS can be interpreted as IS using the product of the original density and a step function as weight function.
- Advantage of OAS is the simple formula for the optimal allocation fractions.
- High dimensional stratification not possible in practice. Thus (like for IS) one (or two) main directions are used for most applications.
- Disadvantage of OAS: Many strata (or an adaptive strata structure) are necessary for rare event simulations.
- Is it possible and sensible to combine IS and OAS to increase the variance reduction?

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Stratified Importance Sampling: Single Estimate Case

- Stratified Importance Sampling (SIS): Applies OAS to an IS algorithm.
- Numerical results for IS of (Sak et al. 2010) and SIS for t -copula model with generalized hyperbolic marginals (parameters estimated from NYSE data)

d	$P(R < t) \approx 0.05$						$P(R < t) \approx 0.001$					
	IS			SIS			IS			SIS		
	VR	TM	ER	VR	TM	ER	VR	TM	ER	VR	TM	ER
2	6.1	0.23	6.5	296.5	0.30	243.5	183.5	0.21	201.7	4741.2	0.28	4046.9
5	8.4	0.79	8.4	110.3	0.90	96.8	278.5	0.79	247.3	3495.7	0.91	2684.9
10	5.3	1.59	5.0	11.4	1.75	9.8	66.6	1.64	60.5	198.3	1.91	154.1

Variance reduction factors: $VR(\hat{x}) = V[\hat{x}_{NV}] / V[\hat{x}]$

Efficiency ratios: $ER(\hat{x}) = VR(\hat{x}) TM[\hat{x}_{NV}] / TM[\hat{x}]$

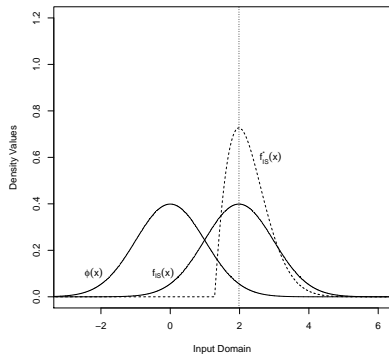
TM execution time, $N \approx 100,000$ for all simulations.

Why works combination of IS and OAS so well?

- IS and OAS use the same direction and are very similar methods.
- We demonstrate their synergy effects for a one-dimensional example

simple example IS

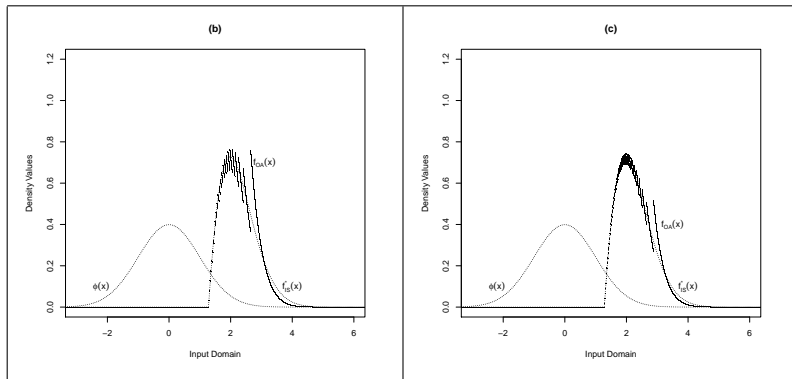
$$y = E_{\phi} [q(Z)], \quad q(x) = \{e^x - 3.6\}^+ \quad \text{and} \quad Z \sim N(0, 1).$$



The original density $\phi(x)$,
the shifted IS density $f_{IS}(x)$ and
the optimal IS density $f_{IS}^*(x)$.

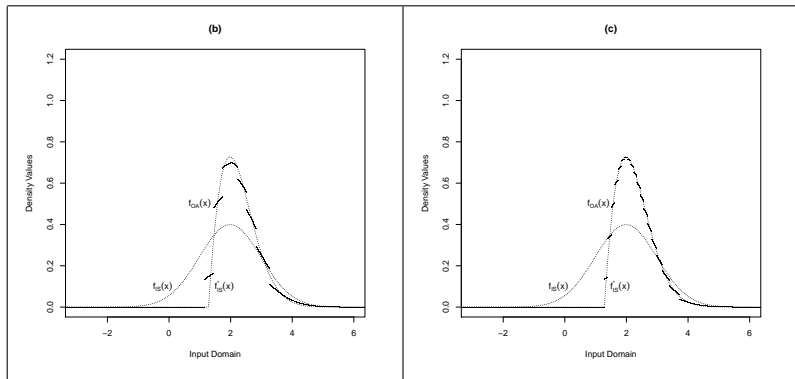
simple example with OAS

IS density corresponding to OAS with 100 and 500 strata.



simple example with SIS

IS density corresponding to SIS with 10 and 25 strata.



simple example: Variance Reduction Factors

Table: Comparison of Naive, IS, OAS 1000, and SIS 100.
exact solution 0.2815896024 .

	Estimate	Variance	VRF
Naive	0.27970	2.17E-05	1
IS	0.28192	3.77E-07	58
OAS 1000	0.28155	2.73E-09	7950
SIS 100	0.28159	8.53E-11	2.5e5

Advantages of combining IS and OAS

We have observed the following advantages when combining IS and OAS for risk simulations:

- IS helps that there are a smaller number of strata with return 0.
- Thus a smaller number of stratification intervals still leads to substantial variance reduction.
- IS helps stratification to obtain better estimates for the variances in the strata and thus better allocation fractions.

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- Stratification can help to estimate many tailloss probabilities for different thresholds τ_j in a single simulation.
That is important when estimating VaR and CVaR.

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Multiple Estimates Case

- Suppose we are interested in probability estimates for distinct threshold values, τ_j , $j = 1, \dots, J$.
- We estimate the j -th tail loss probability and its relative error with the following formula:

$$\hat{x}_j = \sum_{i=1}^I p_i \hat{x}_{ij}, \quad RE [\hat{x}_j] = \frac{\Phi^{-1}(0.975)}{\hat{x}_j \sqrt{N}} \sqrt{\sum_{i=1}^I \frac{p_i^2 \hat{\sigma}_{ij}^2}{\pi_i}}$$

- General questions
 - How should we define the "overall error" of our J estimation problems?
 - How can we minimize that "overall error"?

Multiple Estimates Case

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Definition of Overall Error

$$\hat{x}_{ij} = \text{Prob}(\text{Loss} > \tau_j | X \in \xi_i)$$

$$\hat{x}_j = \text{Prob}(\text{Loss} > \tau_j) = \sum_{i=1}^I p_i \hat{x}_{ij}$$

$$\hat{s}_i^{jk} = \text{Cov}(\hat{x}_{ij}, \hat{x}_{ik}), \quad j, k = 1, \dots, J$$

For the vector $\hat{\mathbf{x}}$ the variance-covariance matrix Σ depends on the allocation fractions:

$$\Sigma_{jk}(\boldsymbol{\pi}) = N^{-1} \sum_{i=1}^I \pi_i^{-1} p_i^2 \hat{s}_i^{jk}.$$

We define an overall error function:

$$\omega(\boldsymbol{\pi}) = g(\Sigma(\boldsymbol{\pi})).$$

Relevant Overall Error functions

- $\omega_{MSE}(\pi) = \sum_{j=1}^J \Sigma_{jj}(\pi)$, the mean squared error of all estimates,
- $\omega_{MSR}(\pi) = \sum_{j=1}^J \hat{x}_j^{-2} \Sigma_{jj}(\pi)$, the mean squared relative error of all estimates,
- $\omega_{MAXE}(\pi) = \max\{j : \Sigma_{jj}(\pi)\}$, the maximum of the squared errors of all estimates,
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mean squared relative error

Using the variances defined above we get:

$$\omega_{MSR}(\boldsymbol{\pi}) = \sum_{j=1}^J \hat{\chi}_j^{-2} \Sigma_{jj}(\boldsymbol{\pi}) = N^{-1} \sum_{i=1}^I \pi_i^{-1} p_i^2 \sum_{j=1}^J \hat{\chi}_j^{-2} \hat{s}_i^{jj},$$

We know from AOS that for a single estimate:

$$V[\hat{\chi}_j] = N^{-1} \sum_{i=1}^I \pi_i^{-1} p_i^2 \sigma_i^2 \geq N^{-1} \left(\sum_{i=1}^I p_i \sigma_i \right)^2.$$

It attains its lower bound for $\pi_i^* = \frac{p_i \sigma_i}{\sum_{k=1}^I p_k \sigma_k}$, $i = 1, \dots, I$.

We can see that $\omega_{MSR}(\boldsymbol{\pi})$ has the same structure as $V[\hat{\chi}_j]$.

Replacing σ_i^2 by $\sum_{j=1}^J \hat{\chi}_j^{-2} \hat{s}_i^{jj}$ we thus can minimize $\omega_{MSR}(\boldsymbol{\pi})$.

mean squared relative error, cont.

$$\omega_{MSR}(\pi) \geq N^{-1} \left(\sum_{i=1}^I p_i \left(\sum_{j=1}^J \hat{x}_j^{-2} \hat{s}_i^{jj} \right)^{1/2} \right)^2$$

$\omega_{MSR}(\pi)$ attains its lower bound selecting

$$\pi_i^* = p_i \left(\sum_{j=1}^J \hat{x}_j^{-2} \hat{s}_i^{jj} \right)^{1/2} / \sum_{l=1}^I p_l \left(\sum_{j=1}^J \hat{x}_j^{-2} \hat{s}_l^{jj} \right)^{1/2}, \quad i = 1, \dots, I.$$

This idea and the closed form solution can be generalized to all $\omega(\pi)$ that are linear functions of the s_i^{jk} .

(Theorem requires non-negativity condition. Assuming positive correlations is no problem for applications to simulation.)

Maximal relative error: Optimization Model

- New objective: Minimize the maximum relative error using the decision variables $\pi = (\pi_1, \dots, \pi_l)'$.
- We denote $\hat{a}_{ij} = \hat{x}_j^{-2} p_i^2 \hat{\sigma}_{ij}^2$ and add constraints which guarantee that the π_i are positive and sum to one.

$$\begin{array}{ll}
 \min & \max \left\{ j: \sum_{i=1}^l \frac{\hat{a}_{ij}}{\pi_i} \right\} \\
 \text{s.t.} & \sum_{i=1}^l \pi_i = 1, \\
 & \pi_i > 0, \quad i = 1, \dots, l.
 \end{array}
 \quad \Rightarrow \quad
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 \min & \omega \\
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The Allocation Heuristic

- For the previous optimization model, we have developed a heuristic which searches for a suboptimal solution in the convex hull of the respective optimal solutions $\pi^j, j = 1, \dots, J$.

$$\begin{aligned}
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 \text{s.t.} \quad & \omega - \sum_{i=1}^I \frac{\hat{a}_{ij}}{\pi_i} \geq 0, \quad j = 1, \dots, J, \\
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Numerical Results

- We consider $D = 5$ stocks under the t-copula model with Generalized Hyperbolic marginals and $J = 10$ equidistant threshold values.
- For IS we use a mixture of two densities.
- For SIS, we simply used a single IS density selected for the threshold $\tau^* = 0.75\tau_{max} + 0.25\tau_{min}$.
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Numerical Results cont.

- Following table shows the percentage relative errors and the variance reduction factors obtained under NV, IS and SIS. The execution times are 0.75, 0.95 and 1.25 seconds respectively.

τ	$\Pr(r(\mathbf{T}) \leq \tau)$	NV	IS		SIS	
		RE	RE	VR	RE	VR
0.895	0.0010	$\pm 19.89\%$	$\pm 2.65\%$	56.3	$\pm 0.77\%$	667.2
0.909	0.0014	$\pm 16.67\%$	$\pm 2.37\%$	49.5	$\pm 0.70\%$	567.1
0.917	0.0020	$\pm 14.13\%$	$\pm 2.12\%$	44.4	$\pm 0.69\%$	419.4
0.924	0.0028	$\pm 12.09\%$	$\pm 1.89\%$	40.9	$\pm 0.68\%$	316.1
0.932	0.0040	$\pm 9.89\%$	$\pm 1.77\%$	31.2	$\pm 0.66\%$	224.5
0.939	0.0060	$\pm 7.96\%$	$\pm 1.72\%$	21.4	$\pm 0.69\%$	133.1
0.947	0.0094	$\pm 6.46\%$	$\pm 1.82\%$	12.6	$\pm 0.66\%$	95.8
0.954	0.0154	$\pm 4.91\%$	$\pm 2.14\%$	5.3	$\pm 0.65\%$	57.1
0.962	0.0267	$\pm 3.75\%$	$\pm 2.26\%$	2.8	$\pm 0.64\%$	34.3
0.973	0.0500	$\pm 2.69\%$	$\pm 9.23\%$	0.1	$\pm 0.69\%$	15.2

Estimating Conditional Excess

- Simulating the conditional excess: $E[\text{Loss} | \text{Loss} \geq \tau]$ requires a ratio estimate; this makes variance reduction more difficult.
- Literature: "Use the same IS density as for tail-loss probabilities."
- The variance of the ratio estimate:

$$V[\hat{x}_1/\hat{x}_2] \approx \hat{x}_1^2 \hat{x}_2^{-4} \Sigma_{22}(\pi) - 2\hat{x}_1 \hat{x}_2^{-3} \Sigma_{12}(\pi) + \hat{x}_2^{-2} \Sigma_{11}(\pi) = \omega(\pi).$$
- To reach optimal allocation for stratification we can use the theorem above to minimize the variance of a ratio estimate.

For Conditional Excess we obtained stratification and stratified IS algorithms with optimal allocation for:

- a single threshold
- for several thresholds minimizing the mean squared relative error.

Conclusions

- For practically relevant examples SIS (combination of IS and stratification) increases the efficiency of tail loss probability estimates under the t -copula model.
- Compared to the methods in the literature, the variance of the estimates are substantially reduced without a significant increase in the execution time.
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- The mean square (relative) error of all estimates can be minimized using the variance estimates of a pilot run and a simple closed form formula for the allocation fractions.
- To minimize the maximal squared (relative) error of all estimates we have developed a fast and simple heuristic to find close to optimal allocation fractions.
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Questions?

THANK YOU !

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