WIRTSCHAFTS


## Finite Mixture Modelling

Model Specification, Estimation \& Application

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## Finite mixture models

Types of applications:

- semi-parametric tool to estimate general distribution functions
- modeling unobserved heterogeneity


## Special cases:

- model-based clustering
- mixtures of regression models


## Finite mixture models

The finite mixture distribution is given by

$$
H(\boldsymbol{y} \mid \boldsymbol{x}, \Theta)=\sum_{k=1}^{K} \pi_{k} F_{k}\left(\boldsymbol{y} \mid \boldsymbol{x}, \boldsymbol{\vartheta}_{k}\right)
$$

with

$$
\sum_{k=1}^{K} \pi_{k}=1 \quad \wedge \quad \pi_{k}>0 \forall k
$$

In the following it is assumed that the component specific density functions $f_{k}$ exist and determine the mixture density $h$.

Finite mixture models



Finite mixture models



## Estimation

Maximum-Likelihood: Expectation-Maximization (EM) Algorithm (Dempster, Laird and Rubin, 1977)

- General method for ML estimation in models with unobserved latent variables: The complete likelihood containing the observed and unobserved data is easier to estimate.
- Iterates between
- E-step, which computes the expectation of the complete likelihood, and
- M-step, where the expected complete likelihood is maximized.


## Bayesian: Gibbs sampling (Diebolt and Robert, 1994)

- Markov Chain Monte Carlo algorithm
- Applicable when the joint posterior distribution is not known explicitly, but the conditional posterior distributions of each variable/subsets of variables are known.


## Missing data

The component-label vectors $z_{n}=\left(z_{n k}\right)_{k=1, \ldots, K}$ are treated as missing data. It holds that

- $z_{n k} \in\{0,1\}$ and
- $\sum_{k=1}^{K} z_{n k}=1$ for all $k=1, \ldots, K$.

The complete log-likelihood is given by

$$
\log L_{c}(\Theta)=\sum_{k=1}^{K} \sum_{n=1}^{N} z_{n k}\left[\log \pi_{k}+\log f_{k}\left(\boldsymbol{y}_{n} \mid \boldsymbol{x}_{n}, \boldsymbol{\vartheta}_{k}\right)\right]
$$

## EM algorithm: M-step

The next parameter estimate is given by:

$$
\Theta^{(i+1)}=\underset{\Theta}{\arg \max } Q\left(\Theta ; \Theta^{(i)}\right)
$$

The estimates for the prior class probabilities are given by:

$$
\pi_{k}^{(i+1)}=\frac{1}{N} \sum_{n=1}^{N} \widehat{z}_{n k}^{(i)}
$$

The component specific parameter estimates are determined by:

$$
\boldsymbol{\vartheta}_{k}^{(i+1)}=\underset{\boldsymbol{\vartheta}_{k}}{\arg \max } \sum_{n=1}^{N} \hat{z}_{n k}^{(i)} \log \left(f_{k}\left(\boldsymbol{y}_{n} \mid \boldsymbol{x}_{n}, \boldsymbol{\vartheta}_{k}\right)\right) .
$$

$\Rightarrow$ weighted ML estimation of the component specific model.

## EM algorithm: E-step

Given the current parameter estimates $\Theta^{(i)}$ replace the missing data $z_{n k}$ by the estimated a-posteriori probabilities

$$
\widehat{z}_{n k}^{(i)}=\mathbb{P}\left(k \mid \boldsymbol{y}_{n}, \boldsymbol{x}_{n}, \boldsymbol{\Theta}^{(i)}\right)=\frac{\pi_{k}^{(i)} f_{k}\left(\boldsymbol{y}_{n} \mid \boldsymbol{x}_{n}, \boldsymbol{\vartheta}_{k}^{(i)}\right)}{\sum_{u=1}^{K} \pi_{u}^{(i)} f_{k}\left(\boldsymbol{y}_{n} \mid \boldsymbol{x}_{n}, \boldsymbol{\vartheta}_{u}^{(i)}\right)} .
$$

The conditional expectation of $\log L_{c}(\Theta)$ at the $i^{\text {th }}$ step is given by

$$
\begin{aligned}
Q\left(\Theta ; \Theta^{(i)}\right) & =\mathbb{E}_{\Theta(i)}\left[\log L_{c}(\Theta) \mid \boldsymbol{y}, \boldsymbol{x}\right] \\
& =\sum_{k=1}^{K} \sum_{n=1}^{N} \hat{z}_{n k}^{(i)}\left[\log \pi_{k}+\log f_{k}\left(\boldsymbol{y}_{n} \mid \boldsymbol{x}_{n}, \boldsymbol{\vartheta}_{k}\right)\right]
\end{aligned}
$$

## M-step: Mixtures of Gaussian distributions

The solutions for the M-step are given in closed form:

$$
\begin{aligned}
\boldsymbol{\mu}_{k}^{(i+1)} & =\frac{\sum_{n=1}^{N} \hat{z}_{n k}^{(i)} \boldsymbol{y}_{n}}{\sum_{n=1}^{N} \bar{z}_{n k}^{(i)}} \\
\Sigma_{k}^{(i+1)} & =\frac{\sum_{n=1}^{N} \bar{z}_{n k}^{(i)}\left(\boldsymbol{y}_{n}-\boldsymbol{\mu}_{k}^{(i+1)}\right)\left(\boldsymbol{y}_{n}-\boldsymbol{\mu}_{k}^{(i+1)}\right)^{\prime}}{\sum_{n=1}^{N} \widehat{z}_{n k}^{(i)}}
\end{aligned}
$$

## Estimation: EM algorithm

## Advantages:

- The likelihood is increased in each step $\rightarrow \mathrm{EM}$ algorithm converges for bounded likelihoods.
- Relatively easy to implement:
- Different mixture models require only different $M$-steps.
- Weighted ML estimation of the component specific model is sometimes already available.

Disadvantages:

- Standard errors have to be determined separately as the information matrix is not required during the algorithm.
- Convergence only to a local optimum
- Slow convergence
$\Rightarrow$ variants such as Stochastic EM (SEM) or Classification EM (CEM)


## Bayesian estimation

Determine the posterior density using Bayes' theorem

$$
p(\Theta \mid \boldsymbol{Y}, \boldsymbol{X}) \propto h(\boldsymbol{Y} \mid \boldsymbol{X}, \Theta) p(\Theta)
$$

where $p(\Theta)$ is the prior and $\boldsymbol{Y}=\left(\boldsymbol{y}_{n}\right)_{n}$ and $\boldsymbol{X}=\left(\boldsymbol{x}_{n}\right)_{n}$.
Standard prior distributions:

- Proper priors: Improper priors give improper posteriors.
- Independent priors for the component weights and the component specific parameters.
- Conjugate priors for the complete likelihood
- Dirichlet distribution $\mathcal{D}\left(e_{0,1}, \ldots, e_{0, K}\right)$ for the component weights which is the conjugate prior for the multinomial distribution.
- Priors on the component specific parameters depend on the underlying distribution family.
- Invariant priors, e.g. the parameter for the Dirchlet prior is constant over all components: $e_{0, k} \equiv e_{0}$

Information criteria: e.g. AIC, BIC, ICL

Likelihood ratio test statistic: Comparison of nested models where the smaller model is derived by fixing one parameter at the border of the parameter space.
$\Rightarrow$ Regularity conditions are not fulfilled.
The asymptotic null distribution is not the usual $\chi^{2}$-distribution with degrees of freedom equal to the difference beween the number of parameters under the null and alternative hypotheses.

- distributional results for special cases
- bootstrapping


## Estimation: Gibbs sampling

Starting with $Z^{0}=\left(z_{n}^{0}\right)_{n=1, \ldots, N}$ repeat the following steps for $i=$ $1, \ldots, I_{0}, \ldots, I+I_{0}$.

1. Parameter simulation conditional on the classification $\boldsymbol{Z}^{(i-1)}$ :
(a) Sample $\pi_{1}, \ldots, \pi_{K}$ from $\mathcal{D}\left(\left(\sum_{n=1}^{N} z_{n k}^{(i-1)}+e_{0, k}\right)_{k=1, \ldots, K}\right)$.
(b) Sample component specific parameters from the complete-data posterior $p\left(\vartheta_{1}, \ldots, \vartheta_{K} \mid \boldsymbol{Z}^{(i-1)}, \boldsymbol{Y}\right)$
Store the actual values of all parameters $\Theta^{(i)}=\left(\pi_{k}^{(i)}, \boldsymbol{\vartheta}_{k}^{(i)}\right)_{k=1, \ldots, K}$.
2. Classification of each observation ( $\boldsymbol{y}_{n}, \boldsymbol{x}_{n}$ ) conditional on knowing $\Theta^{(i)}$ :
Sample $\boldsymbol{z}_{n}^{(i)}$ from the multinomial distribution with parameter equal to the posterior probabilities.

After discarding the burn-in draws the draws $I_{0}+1, \ldots, I+I_{0}$ can be used to approximate all quantities of interest.

## Example: Gaussian distribution

Assume an independence prior

$$
p\left(\boldsymbol{\mu}_{k}, \Sigma_{k}^{-1}\right) \sim f_{N}\left(\boldsymbol{\mu}_{k} ; \boldsymbol{b}_{0}, \boldsymbol{B}_{0}\right) f_{W}\left(\Sigma_{k}^{-1} ; c_{0}, \boldsymbol{C}_{0}\right)
$$

1. Parameter simulation conditional on the classification $\boldsymbol{Z}^{(i-1)}$ :
(a) Sample $\pi_{1}^{(i)}, \ldots, \pi^{(i)}$ from $\mathcal{D}\left(\left(\sum_{n=1}^{N} z_{n k}^{(i-1)}+e_{0, k}\right)_{k=1, \ldots, K}\right)$.
(b) Sample $\left(\sum^{-1}\right)^{(i)^{K}}$ in each group $k$ from a Wishar
(b) Sample $\left(\sum_{k}^{-1}\right)^{i}$ in each group $k$ from a Wishar $\mathcal{W}\left(c_{k}\left(\boldsymbol{Z}^{(i-1)}\right), \boldsymbol{C}_{k}\left(\boldsymbol{Z}^{(i-1)}\right)\right)$ distribution.
(c) Sample $\boldsymbol{\mu}_{k}^{(i)}$ in each group $k$ from a $\mathcal{N}\left(\boldsymbol{b}_{k}\left(\boldsymbol{Z}^{(i-1)}\right), \boldsymbol{B}_{k}\left(\boldsymbol{Z}^{(i-1)}\right)\right)$ distribution.
2. Classification of each observation $\boldsymbol{y}_{n}$ conditional on knowing $\Theta^{(i)}$ :

$$
\mathbb{P}\left(z_{n k}^{(i)}=1 \mid \boldsymbol{y}_{n}, \Theta^{(i)}\right) \propto \pi_{k} f_{N}\left(\boldsymbol{y}_{n} ; \boldsymbol{\mu}_{k}, \Sigma_{k}\right)
$$

## Estimation: Gibbs sampling

## Advantages:

- Relatively easy to implement
- Different mixture models differ only in the parameter simulation step.
- Parameter simulation conditional on the classification is sometimes already available.


## Disadvantages:

- Might fail to escape the attraction area of one mode $\rightarrow$ not all posterior modes are visited.


## Label switching

The posterior distribution is invariant under a permutation of the components with the same component-specific model.
$\Rightarrow$ Determine a unique labelling for component-specific inference:

- Impose a suitable ordering constraint, e.g. $\pi_{s}<\pi_{t} \forall s, t \in\{1, \ldots, S\}$ with $s<t$.
- Minimize the distance to the Maximum-A-Posteriori (MAP) estimate.
- Fix the component membership for some observations.
- Relabelling algorithms.


## Initialization

- Construct a suitable parameter vector $\Theta^{(0)}$.
- random
- other estimation methods: e.g. moment estimators
- Classify observations/assign a-posteriori probabilities to each observation.
- random
- cluster analysis results: e.g. hierarchical clustering, $k$-means


## Software in $\mathbf{R}$

- Model-based clustering
- mclust (Fraley and Raftery, 2002) for Gaussian mixtures:
* specify different models depending on the structure of the variance-covariance matrices (volume, shape, orientation)

$$
\Sigma_{k}=\lambda_{k} D_{k} \operatorname{diag}\left(\boldsymbol{a}_{k}\right) D_{k}^{\prime}
$$

* initialize EM algorithm with the solution from an agglomerative hierarchical clustering algorithm
- Clusterwise regression:
- flexmix (Leisch, 2004)

See also CRAN Task View "Cluster Analysis \& Finite Mixture Models".

## Extensions and special cases

- Model-based clustering:
- Latent class analysis: multivariate discrete observations where the marginal distributions in the components are independent.
- mixtures of factor analyzers
- mixtures of $t$-distributions
- Mixtures of regressions:
- mixtures of generalized linear models
- mixtures of generalized linear mixed models
- Covariates for the component sizes: concomitant variable models
- Impose equality constraints between component-specific parameters


## Software: FlexMix

- The function flexmix() provides the E-step and all data handling
- The M-step is supplied by the user similar to $g \operatorname{lm}()$ families.
- Multiple independent responses from different families
- Currently bindings to several GLM families exist (Gaussian, Poisson, Gamma, Binomial)
- Weighted, hard (CEM) and random (SEM) classification
- Components with prior probability below a user-specified threshold are automatically removed during iteration
- Primary goal is extensibility: ideal for trying out new mixture models.
- No replacement of specialized mixtures like mclust(), but complement.
- Usage of S4 classes and methods
- Formula-based interface
- Multivariate responses:
combination of univariate families: assumption of independence (given $x$ ), each response may have its own model formula, i.e., a different set of regressors
multivariate families: if family handles multivariate response directly, then arbitrary multivariate response distributions are possible


## Example: Clustering



> library("flexmix")
> data("diabetes", package = "mclust")
> diabetes_data <- as.matrix(diabetes[, 2:4])

## Example: Clustering

```
> (mix <- stepFlexmix(diabetes_data ~ 1, k = 1:5,
+ model = FLXMCmvnorm(diag = FALSE),
    nrep = 10))
    ***********
: **********
:**********
5:************
Call:
stepFlexmix(diabetes_data ~ 1, model = FLXMCmvnorm(diag = FALSE)
    k = 1:5, nrep = 10)
iter converged k k0 logLik AIC BIC ICL
1 2 TRUE 1 1 -2545.833 5109.666 5136.456 5136.456
2 12 TRUE 2 2 -2354.674 4747.347 4803.905 4811.644
24 TRUE 3 3-2303.557 4665.113 4751.439 4770.353
4 TRUE 4 4 -2287.605 4653.210 4769.302 4793.502
5 60 TRUE 5 5 -2274.655 4647.309 4793.169 4822.905
> plot(mix)
```


## Example: Clustering



## Example: Clustering



```
> (mix_best <- getModel(mix))
Call:
stepFlexmix(diabetes_data ~ 1, model = FLXMCmvnorm(diag = FALSE),
    k = 3, nrep = 10)
Cluster sizes:
    1 2 3
82 28 35
convergence after 24 iterations
> summary(mix_best)
Call:
stepFlexmix(diabetes_data ~ 1, model = FLXMCmvnorm(diag = FALSE)
    k = 3, nrep = 10)
            prior size post>0 ratio
Comp.1 0.540 82 101 0.812
Comp.2 0.199 28 96 0.292
Comp.2 
'log Lik.' -2303.557 (df=29)
AIC: 4665.113 BIC: 4751.439
```


## Example: Clustering

> table(cluster(getModel(mix)), diabetes\$class)
chemical normal overt

| 1 | 10 | 72 | 0 |
| ---: | ---: | ---: | ---: |
| 2 | 1 | 0 | 27 |

$$
\begin{array}{rrrr}
2 & 1 & 0 & 21 \\
3 & 25 & 4 & 6
\end{array}
$$

$>$ parameters(mix_best, component $=1$, simplify $=$ FALSE)
\$center
glucose insulin sspg
$91.00937358 .19098 \quad 164.14443$
\$cov
glucose insulin
lucose $58.21456 \quad 80.1404 \quad 16.8295$
insulin $80.140392154 .9810 \quad 347.6972$ sspg 16.82950347 .6972 2484.1538
> plot(mix_best, mark = 2)

## Example: Clustering

Rootogram of posterior probabilities $\mathbf{>} \mathbf{1 e - 0 4}$


## Example: Regression

```
> data("aphids", package = "mixreg")
> (mix <- stepFlexmix(n.inf ~ n.aphids, k = 2, data = aphids,
+ nrep = 10))
Call:
stepFlexmix(n.inf ~ n.aphids, data = aphids, k = 2, nrep = 10)
Cluster sizes:
1 2
2328
convergence after 17 iterations
```

Example: Regression


## Example: Regression

> posterior(mix) [1:4,]
[,2]
$[1]$,
[2,] 0.99497690 .005023128
[3,] 0.20980200 .79019802
[4,] 0.20503830 .794961704
> predict(mix, newdata $=$ data.frame(n.aphids $=c(0,300))$ )
\$Comp. 1
[, 1]
1
220.047842
\$Comp. 2
10.8679776
21.5740946

## Example: Regression



## Example: Regression



## Example: Regression

| > refit(mix) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Call: } \\ & \text { refit(mix) } \end{aligned}$ |  |  |  |  |
| Number of components: 2 |  |  |  |  |
| \$Comp. 1 |  |  |  |  |
|  | Estimate | Std. Error | z value | $\operatorname{Pr}(>\|z\|)$ |
| (Intercept) | 3.4585759 | 1.3730364 | 2.5189 | 0.01177 |
| n.aphids | 0.0552974 | 0.0090624 | 6.1019 | $1.048 \mathrm{e}-09$ |
| \$Comp. 2 |  |  |  |  |
|  | Estimate | Std. Error | $z$ value | $\operatorname{Pr}(>\|z\|)$ |
| (Intercept) | 0.8679003 | 0.5017007 | 1.7299 | 0.08365 |
| n.aphids | 0.0023539 | 0.0035375 | 0.6654 | 0.50578 |
| > plot(refit(mix)) |  |  |  |  |

## Applications

Market segmentation: find groups of customers who share

- characteristics: e.g. groups of tourists with similar behaviours at their destination
- reactions: e.g. customers with similar price and other marketing mix elasticities in choice models
$\Rightarrow$ account for heterogeneity between customers
$\Rightarrow$ develop segment-specific marketing strategies


## Monographs

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