Chapter 7

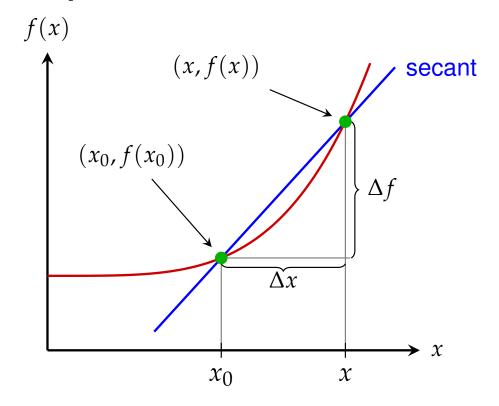
Derivatives

Difference Quotient

Let $f: \mathbb{R} \to \mathbb{R}$ be some function. Then the ratio

$$\frac{\Delta f}{\Delta x} = \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} = \frac{f(x) - f(x_0)}{x - x_0}$$

is called **difference quotient**.



Differential Quotient

If the *limit*

$$\lim_{\Delta x \to 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} = \lim_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

exists, then function f is called **differentiable** at x_0 . This limit is then called **differential quotient** or **(first) derivative** of function f at x_0 .

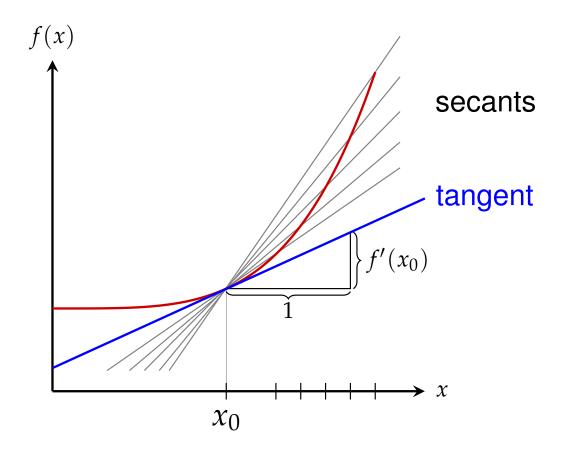
We write

$$f'(x_0)$$
 or $\left. \frac{df}{dx} \right|_{x=x_0}$

Function f is called *differentiable*, if it is differentiable at each point of its domain.

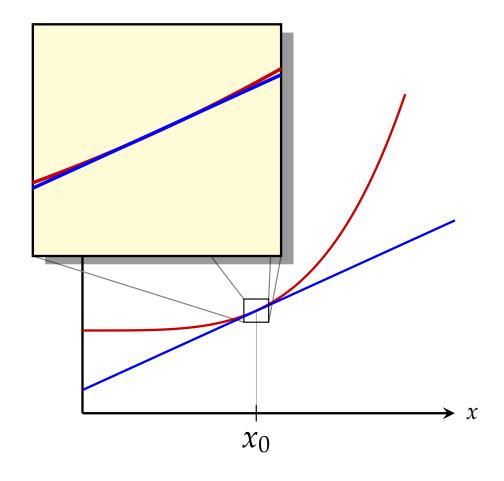
Slope of Tangent

The differential quotient gives the *slope of the tangent* to the graph of function f(x) at x_0 .



Marginal Function

- ightharpoonup Instantaneous change of function f.
- ► "Marginal function" (as in *marginal utility*)



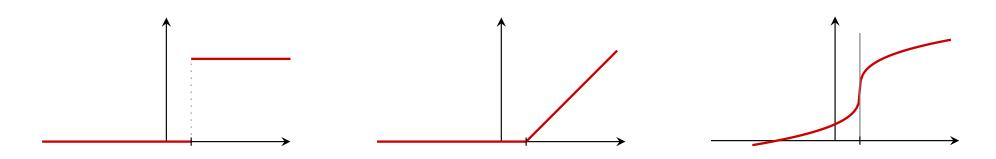
Existence of Differential Quotient

Function f is differentiable at all points, where we can draw the tangent (with finite slope) uniquely to the graph.

Function f is *not* differentiable at all points where this is not possible.

In particular these are

- jump discontinuities
- "kinks" in the graph of the function
- vertical tangents



Computation of the Differential Quotient

We can compute a differential quotient by determining the limit of the difference quotient.

Let $f(x) = x^2$. The we find for the first derivative

$$f'(x_0) = \lim_{h \to 0} \frac{(x_0 + h)^2 - x_0^2}{h}$$

$$= \lim_{h \to 0} \frac{x_0^2 + 2x_0h + h^2 - x_0^2}{h}$$

$$= \lim_{h \to 0} \frac{2x_0h + h^2}{h} = \lim_{h \to 0} (2x_0 + h)$$

$$= 2x_0$$

Draw (sketch) the graphs of the following functions. At which points are these function differentiable?

(a)
$$f(x) = 2x + 2$$

(b)
$$f(x) = 3$$

(c)
$$f(x) = |x|$$

(d)
$$f(x) = \sqrt{|x^2 - 1|}$$

(e)
$$f(x) = \begin{cases} -\frac{1}{2}x^2, & \text{for } x \le -1, \\ x, & \text{for } -1 < x \le 1, \\ \frac{1}{2}x^2, & \text{for } x > 1. \end{cases}$$

(f)
$$f(x) = \begin{cases} 2+x, & \text{for } x \leq -1, \\ x^2, & \text{for } x > -1. \end{cases}$$

Derivative of a Function

Function

$$f': D \to \mathbb{R}, \ x \mapsto f'(x) = \frac{df}{dx}\Big|_{x}$$

is called the **first derivative** of function f. Its domain D is the set of all points where the differential quotient (i.e., the limit of the difference quotient) exists.

Derivatives of Elementary Functions

f(x)	f'(x)
С	0
χ^{α}	$\alpha \cdot x^{\alpha-1}$
e^{x}	e^{x}
ln(x)	$\frac{1}{x}$
$\sin(x)$	$\cos(x)$
$\cos(x)$	$-\sin(x)$

Computation Rules for Derivatives

$$(c \cdot f(x))' = c \cdot f'(x)$$

►
$$(f(x) + g(x))' = f'(x) + g'(x)$$

Summation rule

$$(f(x) \cdot g(x))' = f'(x) \cdot g(x) + f(x) \cdot g'(x)$$

Product rule

$$(f(g(x)))' = f'(g(x)) \cdot g'(x)$$

Chain rule

Quotient rule

Computation Rules for Derivatives

$$(3x^3 + 2x - 4)' = 3 \cdot 3 \cdot x^2 + 2 \cdot 1 - 0 = 9x^2 + 2$$

$$(e^x \cdot x^2)' = (e^x)' \cdot x^2 + e^x \cdot (x^2)' = e^x \cdot x^2 + e^x \cdot 2x$$

$$((3x^2+1)^2)' = 2(3x^2+1) \cdot 6x$$

$$(\sqrt{x})' = (x^{\frac{1}{2}})' = \frac{1}{2} \cdot x^{-\frac{1}{2}} = \frac{1}{2\sqrt{x}}$$

$$(a^{x})' = \left(e^{\ln(a)\cdot x}\right)' = e^{\ln(a)\cdot x} \cdot \ln(a) = a^{x} \ln(a)$$

$$\left(\frac{1+x^2}{1-x^3}\right)' = \frac{2x \cdot (1-x^3) - (1+x^2) \cdot 3x^2}{(1-x^3)^2}$$

Higher Order Derivatives

We can compute derivatives of the derivative of a function.

Thus we obtain the

- **second derivative** f''(x) of function f,
- ▶ third derivative f'''(x), etc.,
- ▶ *n*-th derivative $f^{(n)}(x)$.

Other notations:

$$f''(x) = \frac{d^2f}{dx^2}(x) = \left(\frac{d}{dx}\right)^2 f(x)$$

$$f^{(n)}(x) = \frac{d^n f}{dx^n}(x) = \left(\frac{d}{dx}\right)^n f(x)$$

Higher Order Derivatives

The first five derivatives of function

$$f(x) = x^4 + 2x^2 + 5x - 3$$

are

$$f'(x) = (x^4 + 2x^2 + 5x - 3)' = 4x^3 + 4x + 5$$

$$f''(x) = (4x^3 + 4x + 5)' = 12x^2 + 4$$

$$f'''(x) = (12x^2 + 4)' = 24x$$

$$f^{\text{IV}}(x) = (24x)' = 24$$

$$f^{\text{V}}(x) = 0$$

Compute the first and second derivative of the following functions:

(a)
$$f(x) = 4x^4 + 3x^3 - 2x^2 - 1$$

(b)
$$f(x) = e^{-\frac{x^2}{2}}$$

(c)
$$f(x) = \exp\left(-\frac{x^2}{2}\right)$$

(d)
$$f(x) = \frac{x+1}{x-1}$$

Compute the first and second derivative of the following functions:

(a)
$$f(x) = \frac{1}{1+x^2}$$

(b)
$$f(x) = \frac{1}{(1+x)^2}$$

(c)
$$f(x) = x \ln(x) - x + 1$$

(d)
$$f(x) = \ln(|x|)$$

Compute the first and second derivative of the following functions:

(a)
$$f(x) = \tan(x) = \frac{\sin(x)}{\cos(x)}$$

(b)
$$f(x) = \cosh(x) = \frac{1}{2}(e^x + e^{-x})$$

(c)
$$f(x) = \sinh(x) = \frac{1}{2}(e^x - e^{-x})$$

(d)
$$f(x) = \cos(1 + x^2)$$

Derive the quotient rule by means of product rule and chain rule.

Marginal Change

We can estimate the derivative $f'(x_0)$ approximately by means of the difference quotient with *small* change Δx :

$$f'(x_0) = \lim_{\Delta x \to 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} \approx \frac{\Delta f}{\Delta x}$$

Vice verse we can estimate the change Δf of f for *small* changes Δx approximately by the first derivative of f:

$$\Delta f = f(x_0 + \Delta x) - f(x_0) \approx f'(x_0) \cdot \Delta x$$

Beware:

- $ightharpoonup f'(x_0) \cdot \Delta x$ is a *linear function* in Δx .
- lt is the *best possible* approximation of f by a linear function around x_0 .
- ▶ This approximation is useful only for "small" values of Δx .

Differential

Approximation

$$\Delta f = f(x_0 + \Delta x) - f(x_0) \approx f'(x_0) \cdot \Delta x$$

becomes exact if Δx (and thus Δf) becomes *infinitesimally small*. We then write dx and df instead of Δx and Δf , resp.

$$df = f'(x_0) dx$$

Symbols df and dx are called the **differentials** of function f and the independent variable x, resp.

Differential

Differential df can be seen as a linear function in dx. We can use it to compute f approximately around x_0 .

$$f(x_0 + dx) \approx f(x_0) + df$$

Let
$$f(x) = e^x$$
.

Differential of f at point $x_0 = 1$:

$$df = f'(1) dx = e^1 dx$$

Approximation of f(1.1) by means of this differential:

$$\Delta x = (x_0 + dx) - x_0 = 1.1 - 1 = 0.1$$

$$f(1.1) \approx f(1) + df = e + e \cdot 0.1 \approx 2.99$$

Exact value: f(1.1) = 3.004166...

Let $f(x) = \frac{\ln(x)}{x}$.

Compute $\Delta f = f(3.1) - f(3)$ approximately by means of the differential at point $x_0 = 3$.

Compare your approximation to the exact value.

Elasticity

The first derivative of a function gives *absolute* rate of change of f at x_0 . Hence it depends on the scales used for argument and function values.

However, often *relative* rates of change are more appropriate.

We obtain scale invariance and relative rate of changes by

change of function value relative to value of function change of argument relative to value of argument

and thus

$$\lim_{\Delta x \to 0} \frac{\frac{f(x + \Delta x) - f(x)}{f(x)}}{\frac{\Delta x}{x}} = \lim_{\Delta x \to 0} \frac{f(x + \Delta x) - f(x)}{\Delta x} \cdot \frac{x}{f(x)} = f'(x) \cdot \frac{x}{f(x)}$$

Elasticity

The expression

$$\varepsilon_f(x) = x \cdot \frac{f'(x)}{f(x)}$$

is called the **elasticity** of f at point x.

Let $f(x) = 3e^{2x}$. Then

$$\varepsilon_f(x) = x \cdot \frac{f'(x)}{f(x)} = x \cdot \frac{6e^{2x}}{3e^{2x}} = 2x$$

Let $f(x) = \beta x^{\alpha}$. Then

$$\varepsilon_f(x) = x \cdot \frac{f'(x)}{f(x)} = x \cdot \frac{\beta \alpha x^{\alpha - 1}}{\beta x^{\alpha}} = \alpha$$

Elasticity II

The relative rate of change of f can be expressed as

$$\ln(f(x))' = \frac{f'(x)}{f(x)}$$

What happens if we compute the derivative of ln(f(x)) w.r.t. ln(x)?

Let
$$v = \ln(x) \Leftrightarrow x = e^v$$

Derivation by means of the chain rule yields:

$$\frac{d(\ln(f(x)))}{d(\ln(x))} = \frac{d(\ln(f(e^v)))}{dv} = \frac{f'(e^v)}{f(e^v)} e^v = \frac{f'(x)}{f(x)} x = \varepsilon_f(x)$$

$$\varepsilon_f(x) = \frac{d(\ln(f(x)))}{d(\ln(x))}$$

Elasticity II

We can use the chain rule *formally* in the following way:

Let

$$ightharpoonup u = \ln(y),$$

$$ightharpoonup y = f(x),$$

$$ightharpoonup x = e^v \Leftrightarrow v = \ln(x)$$

Then we find

$$\frac{d(\ln f)}{d(\ln x)} = \frac{du}{dv} = \frac{du}{dy} \cdot \frac{dy}{dx} \cdot \frac{dx}{dv} = \frac{1}{y} \cdot f'(x) \cdot e^{v} = \frac{f'(x)}{f(x)} x$$

Elastic Functions

A Function f is called

- ▶ elastic in x, if $|\varepsilon_f(x)| > 1$
- ▶ 1-elastic in x, if $|\varepsilon_f(x)| = 1$
- ▶ inelastic in x, if $|\varepsilon_f(x)| < 1$

For elastic functions we then have:

The value of the function changes *relatively* faster than the value of the argument.

Function
$$f(x) = 3e^{2x}$$
 is

[
$$\varepsilon_f(x) = 2x$$
]

- ▶ 1-elastic, for $x = -\frac{1}{2}$ and $x = \frac{1}{2}$;
- ▶ inelastic, for $-\frac{1}{2} < x < \frac{1}{2}$;
- ightharpoonup elastic, for $x < -\frac{1}{2}$ or $x > \frac{1}{2}$.

Source of Errors

Beware!

Function f is elastic if the **absolute value** of the *elasticity* is greater than 1.

Elastic Demand

Let q(p) be an *elastic* demand function, where p is the price. We have: p > 0, q > 0, and q' < 0 (q is decreasing). Hence

$$\varepsilon_q(p) = p \cdot \frac{q'(p)}{q(p)} < -1$$

What happens to the revenue (= price \times selling)?

$$u'(p) = (p \cdot q(p))' = 1 \cdot q(p) + p \cdot q'(p)$$

$$= q(p) \cdot (1 + p \cdot \frac{q'(p)}{q(p)})$$

$$= \varepsilon_q < -1$$

$$< 0$$

In other words, the revenue decreases if we raise prices.

Compute the regions where the following functions are elastic, 1-elastic and inelastic, resp.

(a)
$$g(x) = x^3 - 2x^2$$

(b)
$$h(x) = \alpha x^{\beta}, \quad \alpha, \beta \neq 0$$

Which of the following statements are correct? Suppose function y = f(x) is elastic in its domain.

- (a) If x changes by one unit, then the change of y is greater than one unit.
- (b) If x changes by one percent, then the relative change of y is greater than one percent.
- (c) The relative rate of change of y is larger than the relative rate of change of x.
- (d) The larger x is the larger will be y.

Partial Derivative

We investigate the rate of change of function $f(x_1, ..., x_n)$, when variable x_i changes and the other variables remain fixed. Limit

$$\frac{\partial f}{\partial x_i} = \lim_{\Delta x_i \to 0} \frac{f(\dots, x_i + \Delta x_i, \dots) - f(\dots, x_i, \dots)}{\Delta x_i}$$

is called the (first) **partial derivative** of f w.r.t. x_i .

Other notations for partial derivative $\frac{\partial f}{\partial x_i}$:

- $ightharpoonup f_{x_i}(\mathbf{x})$ (derivative w.r.t. variable x_i)
- ► $f_i(\mathbf{x})$ (derivative w.r.t. the *i*-th variable)
- ► $f'_i(\mathbf{x})$ (*i*-th component of the gradient)

Computation of Partial Derivatives

We obtain partial derivatives $\frac{\partial f}{\partial x_i}$ by applying the rules for *univariate* functions for variable x_i while we treat *all other* variables *as constants*.

First partial derivatives of

$$f(x_1, x_2) = \sin(2x_1) \cdot \cos(x_2)$$

$$f_{x_1} = 2 \cdot \cos(2x_1) \cdot \cos(x_2)$$
treated as constant
$$f_{x_2} = \sin(2x_1) \cdot (-\sin(x_2))$$
treated as constant

Higher Order Partial Derivatives

We can compute partial derivatives of partial derivatives analogously to their univariate counterparts and obtain

higher order partial derivatives:

$$\frac{\partial^2 f}{\partial x_k \partial x_i}(\mathbf{x})$$
 and $\frac{\partial^2 f}{\partial x_i^2}(\mathbf{x})$

Other notations for partial derivative $\frac{\partial^2 f}{\partial x_k \partial x_i}(\mathbf{x})$:

- ► $f_{x_i x_k}(\mathbf{x})$ (derivative w.r.t. variables x_i and x_k)
- ► $f_{ik}(\mathbf{x})$ (derivative w.r.t. the *i*-th and *k*-th variable)
- ► $f_{ik}^{"}(\mathbf{x})$ (component of the Hessian matrix with index ik)

Higher Order Partial Derivatives

If all second order partial derivatives exists and are *continuous*, then the order of differentiation does not matter (Schwarz's theorem):

$$\frac{\partial^2 f}{\partial x_k \partial x_i}(\mathbf{x}) = \frac{\partial^2 f}{\partial x_i \partial x_k}(\mathbf{x})$$

Remark: Practically all differentiable functions in economic models have this property.

Higher Order Partial Derivatives

Compute the first and second order partial derivatives of

$$f(x,y) = x^2 + 3xy$$

First order partial derivatives:

$$f_x = 2x + 3y \qquad f_y = 0 + 3x$$

Second order partial derivatives:

$$f_{xx} = 2$$
 $f_{xy} = 3$ $f_{yy} = 0$

Compute the first and second order partial derivatives of the following functions at point (1,1):

(a)
$$f(x,y) = x + y$$

(b)
$$f(x,y) = xy$$

(c)
$$f(x,y) = x^2 + y^2$$

(d)
$$f(x,y) = x^2 y^2$$

(e)
$$f(x,y) = x^{\alpha} y^{\beta}$$
, $\alpha, \beta > 0$

Compute the first and second order partial derivatives of

$$f(x,y) = \exp(x^2 + y^2)$$

at point (0,0).

Compute the first and second order partial derivatives of the following functions at point (1,1):

(a)
$$f(x,y) = \sqrt{x^2 + y^2}$$

(b)
$$f(x,y) = (x^3 + y^3)^{\frac{1}{3}}$$

(c)
$$f(x,y) = (x^p + y^p)^{\frac{1}{p}}$$

Gradient

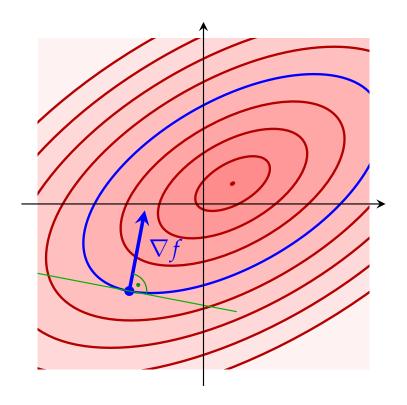
We collect all *first order partial derivatives* into a (row) vector which is called the **gradient** at point x.

$$\nabla f(\mathbf{x}) = (f_{x_1}(\mathbf{x}), \dots, f_{x_n}(\mathbf{x}))$$

- ightharpoonup read: "gradient of f" or "nabla f".
- ▶ Other notation: $f'(\mathbf{x})$
- Alternatively the gradient can also be a column vector.
- The gradient is the analog of the first derivative of univariate functions.

Properties of the Gradient

- ► The gradient of *f* always points in the direction of *steepest ascent*.
- ► Its length is equal to the slope at this point.
- ► The gradient is *normal* (i.e. in right angle) to the corresponding *contour line* (level set).



Gradient

Compute the gradient of

$$f(x,y) = x^2 + 3xy$$

at point x = (3, 2).

$$f_x = 2x + 3y$$

$$f_y = 0 + 3x$$

$$\nabla f(\mathbf{x}) = (2x + 3y, 3x)$$

$$\nabla f(3, 2) = (12, 9)$$

Compute the gradients of the following functions at point (1,1):

(a)
$$f(x,y) = x + y$$

(b)
$$f(x,y) = xy$$

(c)
$$f(x,y) = x^2 + y^2$$

(d)
$$f(x,y) = x^2 y^2$$

(e)
$$f(x,y) = x^{\alpha} y^{\beta}$$
, $\alpha, \beta > 0$

Compute the gradients of the following functions at point (1,1):

(a)
$$f(x,y) = \sqrt{x^2 + y^2}$$

(b)
$$f(x,y) = (x^3 + y^3)^{\frac{1}{3}}$$

(c)
$$f(x,y) = (x^p + y^p)^{\frac{1}{p}}$$

Hessian Matrix

Let $f(\mathbf{x}) = f(x_1, \dots, x_n)$ be two times differentiable. Then matrix

$$\mathbf{H}_{f}(\mathbf{x}) = \begin{pmatrix} f_{x_1x_1}(\mathbf{x}) & f_{x_1x_2}(\mathbf{x}) & \dots & f_{x_1x_n}(\mathbf{x}) \\ f_{x_2x_1}(\mathbf{x}) & f_{x_2x_2}(\mathbf{x}) & \dots & f_{x_2x_n}(\mathbf{x}) \\ \vdots & \vdots & \ddots & \vdots \\ f_{x_nx_1}(\mathbf{x}) & f_{x_nx_2}(\mathbf{x}) & \dots & f_{x_nx_n}(\mathbf{x}) \end{pmatrix}$$

is called the **Hessian matrix** of f at x.

- ► The Hessian matrix is symmetric, i.e., $f_{x_ix_k}(\mathbf{x}) = f_{x_kx_i}(\mathbf{x})$.
- ▶ Other notation: $f''(\mathbf{x})$
- ► The Hessian matrix is the analog of the second derivative of univariate functions.

Gradient

Compute the Hessian matrix of

$$f(x,y) = x^2 + 3xy$$

at point x = (1, 2).

Second order partial derivatives:

$$f_{xx} = 2 f_{xy} = 3$$

$$f_{yx} = 3 f_{yy} = 0$$

Hessian matrix:

$$\mathbf{H}_{f}(x,y) = \begin{pmatrix} f_{xx}(x,y) & f_{xy}(x,y) \\ f_{yx}(x,y) & f_{yy}(x,y) \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 3 & 0 \end{pmatrix} = \mathbf{H}_{f}(1,2)$$

Compute the Hessian matrix of the following functions at point (1,1):

(a)
$$f(x,y) = x + y$$

(b)
$$f(x,y) = xy$$

(c)
$$f(x,y) = x^2 + y^2$$

(d)
$$f(x,y) = x^2 y^2$$

(e)
$$f(x,y) = x^{\alpha} y^{\beta}$$
, $\alpha, \beta > 0$

Compute the Hessian matrix of the following functions at point (1,1):

(a)
$$f(x,y) = \sqrt{x^2 + y^2}$$

(b)
$$f(x,y) = (x^3 + y^3)^{\frac{1}{3}}$$

(c)
$$f(x,y) = (x^p + y^p)^{\frac{1}{p}}$$

Jacobian Matrix

Let
$$\mathbf{f} \colon \mathbb{R}^n \to \mathbb{R}^m$$
, $\mathbf{x} \mapsto \mathbf{y} = \mathbf{f}(\mathbf{x}) = \begin{pmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_m(x_1, \dots, x_n) \end{pmatrix}$

The $m \times n$ matrix

$$D\mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

is called the **Jacobian matrix** of f at point x_0 .

It is the generalization of *derivatives* (and gradients) for vector-valued functions.

Jacobian Matrix

$$f(\mathbf{x}) = f(x_1, x_2) = \exp(-x_1^2 - x_2^2)$$

$$Df(\mathbf{x}) = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}\right) = \nabla f(\mathbf{x})$$

$$= \left(-2x_1 \exp(-x_1^2 - x_2^2), -2x_2 \exp(-x_1^2 - x_2^2)\right)$$

$$\int f(\mathbf{x}) d\mathbf{x} d\mathbf{$$

►
$$\mathbf{f}(\mathbf{x}) = \mathbf{f}(x_1, x_2) = \begin{pmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{pmatrix} = \begin{pmatrix} x_1^2 + x_2^2 \\ x_1^2 - x_2^2 \end{pmatrix}$$

$$D\mathbf{f}(\mathbf{x}) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{pmatrix} = \begin{pmatrix} 2x_1 & 2x_2 \\ 2x_1 & -2x_2 \end{pmatrix}$$

$$\mathbf{s}(t) = \begin{pmatrix} s_1(t) \\ s_2(t) \end{pmatrix} = \begin{pmatrix} \cos(t) \\ \sin(t) \end{pmatrix}$$

$$D\mathbf{s}(t) = \begin{pmatrix} \frac{ds_1}{dt} \\ \frac{ds_2}{dt} \end{pmatrix} = \begin{pmatrix} -\sin(t) \\ \cos(t) \end{pmatrix}$$

Chain Rule

Let $\mathbf{f} \colon \mathbb{R}^n \to \mathbb{R}^m$ and $\mathbf{g} \colon \mathbb{R}^m \to \mathbb{R}^k$. Then

$$(\mathbf{g} \circ \mathbf{f})'(\mathbf{x}) = \mathbf{g}'(\mathbf{f}(\mathbf{x})) \cdot \mathbf{f}'(\mathbf{x})$$

$$\mathbf{f}(x,y) = \begin{pmatrix} e^{x} \\ e^{y} \end{pmatrix} \qquad \mathbf{g}(x,y) = \begin{pmatrix} x^{2} + y^{2} \\ x^{2} - y^{2} \end{pmatrix}$$

$$\mathbf{f}'(x,y) = \begin{pmatrix} e^{x} & 0 \\ 0 & e^{y} \end{pmatrix} \qquad \mathbf{g}'(x,y) = \begin{pmatrix} 2x & 2y \\ 2x & -2y \end{pmatrix}$$

$$(\mathbf{g} \circ \mathbf{f})'(\mathbf{x}) = \mathbf{g}'(\mathbf{f}(\mathbf{x})) \cdot \mathbf{f}'(\mathbf{x}) = \begin{pmatrix} 2e^{x} & 2e^{y} \\ 2e^{x} & -2e^{y} \end{pmatrix} \cdot \begin{pmatrix} e^{x} & 0 \\ 0 & e^{y} \end{pmatrix}$$

$$= \begin{pmatrix} 2e^{2x} & 2e^{2y} \\ 2e^{2x} & -2e^{2y} \end{pmatrix}$$

Example – Indirect Dependency

Let $f(x_1, x_2, t)$ where $x_1(t)$ and $x_2(t)$ also depend on t. What is the total derivative of f w.r.t. t?

 $= f_{x_1}(x_1, x_2, t) \cdot x_1'(t) + f_{x_2}(x_1, x_2, t) \cdot x_2'(t) + f_t(x_1, x_2, t)$

Let

$$f(x,y) = x^2 + y^2$$
 and $\mathbf{g}(t) = \begin{pmatrix} g_1(t) \\ g_2(t) \end{pmatrix} = \begin{pmatrix} t \\ t^2 \end{pmatrix}$.

Compute the derivative of the composite functions

(a)
$$h = f \circ g$$
, and

(b)
$$\mathbf{p} = \mathbf{g} \circ f$$

by means of the chain rule.

Let
$$\mathbf{f}(\mathbf{x}) = \begin{pmatrix} x_1^3 - x_2 \\ x_1 - x_2^3 \end{pmatrix}$$
 and $\mathbf{g}(\mathbf{x}) = \begin{pmatrix} x_2^2 \\ x_1 \end{pmatrix}$.

Compute the derivatives of the composite functions

- (a) $g \circ f$, and
- (b) $f \circ g$

by means of the chain rule.

Let Q(K, L, t) be a production function, where L = L(t) and K = K(t) also depend on time t. Compute the total derivative $\frac{dQ}{dt}$ by means of the chain rule.

Summary

- difference quotient and differential quotient
- differential quotient and derivative
- derivatives of elementary functions
- differentiation rules
- higher order derivatives
- total differential
- elasticity
- partial derivatives
- gradient and Hessian matrix
- ► Jacobian matrix and chain rule