

Chapter 16

Kuhn Tucker Conditions

Constraint Optimization

Find the maximum of function

$$f(x, y)$$

subject to

$$g(x, y) \leq c, \quad x, y \geq 0$$

Example:

Find the maxima of

$$f(x, y) = -(x - 5)^2 - (y - 5)^2$$

subject to

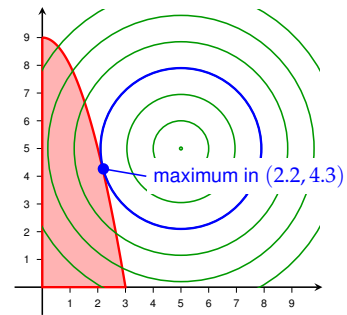
$$x^2 + y \leq 9, \quad x, y \geq 0$$

Graphical Solution

For the case of two variables we can find a solution graphically.

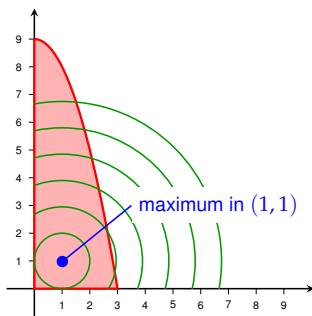
1. Draw the constraint $g(x, y) \leq c$ in the xy -plane (*feasible region*).
2. Draw *appropriate* contour lines of objective function $f(x, y)$.
3. Investigate which contour lines of the objective function intersect with the feasible region.
Estimate the (approximate) location of the maxima.

Example – Graphical Solution



Maximum of $f(x, y) = -(x - 5)^2 - (y - 5)^2$
subject to $g(x, y) = x^2 + y \leq 9, \quad x, y \geq 0$.

Example – Graphical Solution



Maximum of $f(x, y) = -(x - 1)^2 - (y - 1)^2$
subject to $g(x, y) = x^2 + y \leq 9, \quad x, y \geq 0$.

Constraint Optimization

Compute the maximum of function

$$f(x_1, \dots, x_n)$$

subject to

$$g_1(x_1, \dots, x_n) \leq c_1$$

\vdots

$$g_k(x_1, \dots, x_n) \leq c_k$$

$$x_1, \dots, x_n \geq 0 \quad (\text{non-negativity constraint})$$

Optimization problem:

$$\max f(\mathbf{x}) \quad \text{subject to} \quad \mathbf{g}(\mathbf{x}) \leq \mathbf{c} \quad \text{and} \quad \mathbf{x} \geq 0.$$

Non-Negativity Constraint

Univariate function f with non-negativity constraint.

We find for the maximum x^* of f :

- ▶ x^* is an *interior* point of the feasible region:
 $x^* > 0$ and $f'(x^*) = 0$; or
- ▶ x^* is a boundary point of the feasible region:
 $x^* = 0$ and $f'(x^*) \leq 0$.

Summary:

$$f'(x^*) \leq 0, \quad x^* \geq 0 \quad \text{and} \quad x^* f'(x^*) = 0$$



Non-Negativity Constraint

For the case of a multivariate function $f(\mathbf{x})$ with non-negativity constraints $x_j \geq 0$, we obtain such a condition for each of the variables:

$$f_{x_j}(x^*) \leq 0, \quad x_j^* \geq 0 \quad \text{and} \quad x_j^* f_{x_j}(x^*) = 0$$

Slack Variables

Maximize

$$f(x_1, \dots, x_n)$$

subject to

$$g_1(x_1, \dots, x_n) + s_1 = c_1$$

⋮

$$g_k(x_1, \dots, x_n) + s_k = c_k$$

$$x_1, \dots, x_n \geq 0$$

$$s_1, \dots, s_k \geq 0 \quad (\text{new non-negativity constraint})$$

Lagrange function:

$$\tilde{\mathcal{L}}(\mathbf{x}, \mathbf{s}, \boldsymbol{\lambda}) = f(x_1, \dots, x_n) + \sum_{i=1}^k \lambda_i (c_i - g_i(x_1, \dots, x_n) - s_i)$$

Slack Variables

$$\tilde{\mathcal{L}}(\mathbf{x}, \mathbf{s}, \boldsymbol{\lambda}) = f(x_1, \dots, x_n) + \sum_{i=1}^k \lambda_i (c_i - g_i(x_1, \dots, x_n) - s_i)$$

Apply non-negativity conditions:

$$\frac{\partial \tilde{\mathcal{L}}}{\partial x_j} \leq 0, \quad x_j \geq 0 \quad \text{and} \quad x_j \frac{\partial \tilde{\mathcal{L}}}{\partial x_j} = 0$$

$$\frac{\partial \tilde{\mathcal{L}}}{\partial s_i} \leq 0, \quad s_i \geq 0 \quad \text{and} \quad s_i \frac{\partial \tilde{\mathcal{L}}}{\partial s_i} = 0$$

$$\frac{\partial \tilde{\mathcal{L}}}{\partial \lambda_i} = 0 \quad (\text{no non-negativity constraint})$$

Elimination of Slack Variables

Because of $\frac{\partial \tilde{\mathcal{L}}}{\partial s_i} = -\lambda_i$ the second line is equivalent to

$$\lambda_i \geq 0, \quad s_i \geq 0 \quad \text{and} \quad \lambda_i s_i = 0$$

Equations $\frac{\partial \tilde{\mathcal{L}}}{\partial \lambda_i} = c_i - g_i(\mathbf{x}) - s_i = 0$ imply $s_i = c_i - g_i(\mathbf{x})$

and consequently the second line is equivalent to

$$\lambda_i \geq 0, \quad c_i - g_i(\mathbf{x}) \geq 0 \quad \text{and} \quad \lambda_i (c_i - g_i(\mathbf{x})) = 0.$$

Therefore there is no need of slack variables any more.

Elimination of Slack Variables

So we replace $\tilde{\mathcal{L}}$ by Lagrange function

$$\mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}) = f(x_1, \dots, x_n) + \sum_{i=1}^k \lambda_i (c_i - g_i(x_1, \dots, x_n))$$

Observe that

$$\frac{\partial \mathcal{L}}{\partial x_j} = \frac{\partial \tilde{\mathcal{L}}}{\partial x_j} \quad \text{and} \quad \frac{\partial \mathcal{L}}{\partial \lambda_i} = c_i - g_i(\mathbf{x})$$

So the second line of the condition for a maximum now reads

$$\lambda_i \geq 0, \quad \frac{\partial \mathcal{L}}{\partial \lambda_i} \geq 0 \quad \text{and} \quad \lambda_i \frac{\partial \mathcal{L}}{\partial \lambda_i} = 0$$

Kuhn-Tucker Conditions

$$\mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}) = f(x_1, \dots, x_n) + \sum_{i=1}^k \lambda_i (c_i - g_i(x_1, \dots, x_n))$$

The **Kuhn-Tucker conditions** for a (global) maximum are:

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial x_j} &\leq 0, \quad x_j \geq 0 \quad \text{and} \quad x_j \frac{\partial \mathcal{L}}{\partial x_j} = 0 \\ \frac{\partial \mathcal{L}}{\partial \lambda_i} &\geq 0, \quad \lambda_i \geq 0 \quad \text{and} \quad \lambda_i \frac{\partial \mathcal{L}}{\partial \lambda_i} = 0 \end{aligned}$$

Notice that these Kuhn-Tucker conditions are not sufficient. (Analogous to critical points.)

Example – Kuhn-Tucker Conditions

Find the maximum of

$$f(x, y) = -(x-5)^2 - (y-5)^2$$

subject to

$$x^2 + y \leq 9, \quad x, y \geq 0$$

Example – Kuhn-Tucker Conditions

Lagrange function:

$$\mathcal{L}(x, y; \lambda) = -(x-5)^2 - (y-5)^2 + \lambda(9 - x^2 - y)$$

Kuhn-Tucker Conditions:

$$(A) \quad \mathcal{L}_x = -2(x-5) - 2\lambda x \leq 0$$

$$(B) \quad \mathcal{L}_y = -2(y-5) - \lambda \leq 0$$

$$(C) \quad \mathcal{L}_\lambda = 9 - x^2 - y \geq 0$$

$$(N) \quad x, y, \lambda \geq 0$$

$$(I) \quad x \mathcal{L}_x = -x(2(x-5) + 2\lambda x) = 0$$

$$(II) \quad y \mathcal{L}_y = -y(2(y-5) + \lambda) = 0$$

$$(III) \quad \lambda \mathcal{L}_\lambda = \lambda(9 - x^2 - y) = 0$$

Example – Kuhn-Tucker Conditions

Express equations (I)–(III) as

$$(I) \quad x = 0 \quad \text{or} \quad 2(x-5) + 2\lambda x = 0$$

$$(II) \quad y = 0 \quad \text{or} \quad 2(y-5) + \lambda = 0$$

$$(III) \quad \lambda = 0 \quad \text{or} \quad 9 - x^2 - y = 0$$

We have to compute all 8 combinations and check whether the resulting solutions satisfy inequalities (A), (B), (C), and (N).

► If $\lambda = 0$ (III, left), then by (I) and (II) there exist four solutions for $(x, y; \lambda)$:

$$(0, 0; 0), (0, 5; 0), (5, 0; 0), \text{ and } (5, 5; 0).$$

However, none of these points satisfies all inequalities (A), (B), (C).

Hence $\lambda \neq 0$.

Example – Kuhn-Tucker Conditions

If $\lambda \neq 0$, then (III, right) implies $y = 9 - x^2$.

- ▶ If $\lambda \neq 0$ and $x = 0$, then $y = 9$ and because of (II, right), $\lambda = -8$. A contradiction to (N).
- ▶ If $\lambda \neq 0$ and $y = 0$, then $x = 3$ and because of (I, right), $\lambda = \frac{2}{3}$. A contradiction to (B).
- ▶ Consequently all three variables must be non-zero. Thus $y = 9 - x^2$ and $\lambda = -2(y - 5) = -2(4 - x^2)$. Substituted in (I) yields $2(x - 5) - 4(4 - x^2)x = 0$ and $x = \frac{\sqrt{11}+1}{2} \approx 2.158$ $y = \frac{12-\sqrt{11}}{2} \approx 4.342$
 $\lambda = \sqrt{11} - 2 \approx 1.317$

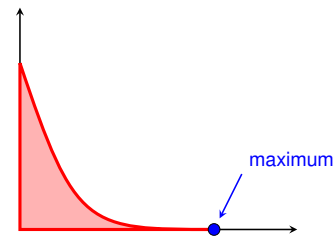
The Kuhn-Tucker conditions are thus satisfied only in point

$$(x, y; \lambda) = \left(\frac{\sqrt{11}+1}{2}, \frac{12-\sqrt{11}}{2}; \sqrt{11} - 2 \right).$$

Kuhn-Tucker Conditions

Unfortunately the Kuhn-Tucker conditions are not necessary!

That is, there exist optimization problems where the maximum does *not* satisfy the Kuhn-Tucker conditions.



Kuhn-Tucker Theorem

We need a tool to determine whether a point is a (global) maximum.

The **Kuhn-Tucker theorem** provides a *sufficient* condition:

- (1) Objective function $f(x)$ is differentiable and **concave**.
- (2) All functions $g_i(x)$ from the constraints are differentiable and **convex**.
- (3) Point x^* satisfy the Kuhn-Tucker conditions.

Then x^* is a *global maximum* of f subject to constraints $g_i \leq c_i$.

The maximum is unique, if function f is *strictly concave*.

Example – Kuhn-Tucker Theorem

Find the maximum of

$$f(x, y) = -(x - 5)^2 - (y - 5)^2$$

subject to

$$x^2 + y \leq 9, \quad x, y \geq 0$$

The respective Hessian matrices of $f(x, y)$ and $g(x, y) = x^2 + y$ are

$$\mathbf{H}_f = \begin{pmatrix} -2 & 0 \\ 0 & -2 \end{pmatrix} \quad \text{and} \quad \mathbf{H}_g = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$

Example – Kuhn-Tucker Theorem

$$\mathbf{H}_f = \begin{pmatrix} -2 & 0 \\ 0 & -2 \end{pmatrix} \quad \text{and} \quad \mathbf{H}_g = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$

- (1) f is strictly concave.
- (2) g is convex.
- (3) Point $(x, y; \lambda) = \left(\frac{\sqrt{11}+1}{2}, \frac{12-\sqrt{11}}{2}; \sqrt{11} - 2 \right)$ satisfy the Kuhn-Tucker conditions.

Thus by the Kuhn-Tucker theorem, $\mathbf{x}^* = \left(\frac{\sqrt{11}+1}{2}, \frac{12-\sqrt{11}}{2} \right)$ is the maximum we sought for.

Summary

- ▶ constraint optimization
- ▶ graphical solution
- ▶ Lagrange function
- ▶ Kuhn-Tucker conditions
- ▶ Kuhn-Tucker theorem