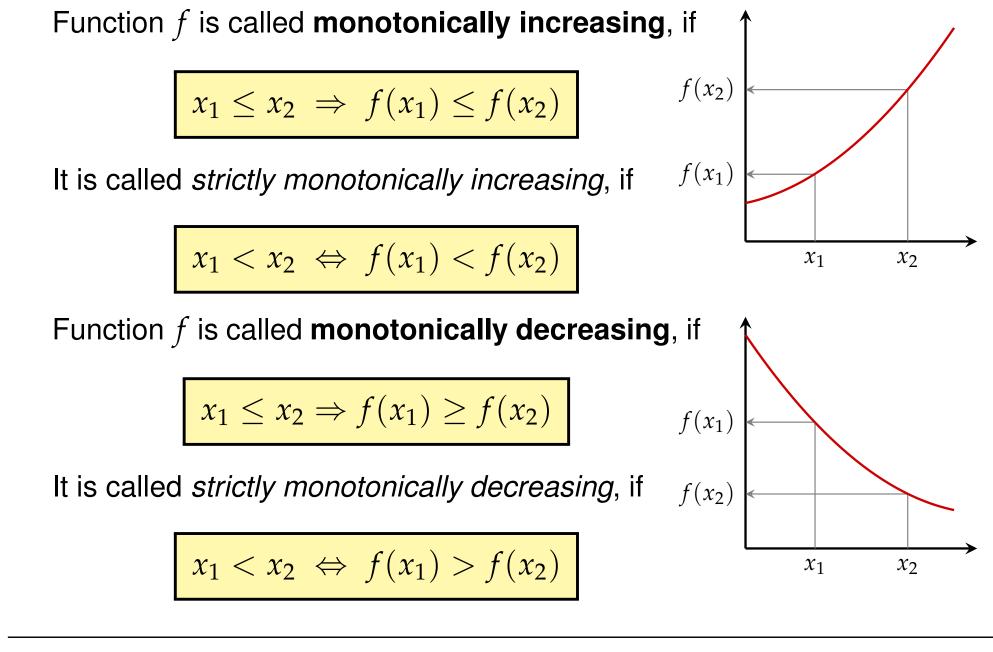
Chapter 13

# **Convex and Concave**

# **Monotone Functions**\*



# **Monotone Functions**\*

For differentiable functions we have

$$f$$
 monotonically increasing  $\Leftrightarrow f'(x) \ge 0$  for all  $x \in D_f$   
 $f$  monotonically decreasing  $\Leftrightarrow f'(x) \le 0$  for all  $x \in D_f$ 

f strictly monotonically increasing  $\Leftrightarrow f'(x) > 0$  for all  $x \in D_f$ f strictly monotonically decreasing  $\Leftrightarrow f'(x) < 0$  for all  $x \in D_f$ 

Function  $f: (0, \infty), x \mapsto \ln(x)$  is strictly monotonically increasing, as

$$f'(x) = (\ln(x))' = \frac{1}{x} > 0$$
 for all  $x > 0$ 

# **Locally Monotone Functions**\*

A function f can be monotonically increasing in some interval and decreasing in some other interval.

For *continuously* differentiable functions (i.e., when f'(x) is continuous) we can use the following procedure:

- **1.** Compute first derivative f'(x).
- **2.** Determine all roots of f'(x).
- **3.** We thus obtain intervals where f'(x) does not change sign.
- **4.** Select appropriate points  $x_i$  in each interval and determine the sign of  $f'(x_i)$ .

# **Example – Locally Monotone Functions\***

In which region is function  $f(x) = 2x^3 - 12x^2 + 18x - 1$ monotonically increasing?

We have to solve inequality  $f'(x) \ge 0$ :

- **1.**  $f'(x) = 6x^2 24x + 18$
- **2.** Roots:  $x^2 4x + 3 = 0 \Rightarrow x_1 = 1, x_2 = 3$
- **3.** Obtain 3 intervals:  $(-\infty, 1], [1, 3], \text{ and } [3, \infty)$
- 4. Sign of f'(x) at appropriate points in each interval: f'(0) = 3 > 0, f'(2) = -1 < 0, and f'(4) = 3 > 0.
- 5. f'(x) cannot change sign in each interval:  $f'(x) \ge 0$  in  $(-\infty, 1]$  and  $[3, \infty)$ .

Function f(x) is monotonically increasing in  $(-\infty, 1]$  and in  $[3, \infty)$ .

# **Monotone and Inverse Function**

If f is strictly monotonically increasing, then

$$x_1 < x_2 \iff f(x_1) < f(x_2)$$

immediately implies

$$x_1 \neq x_2 \iff f(x_1) \neq f(x_2)$$

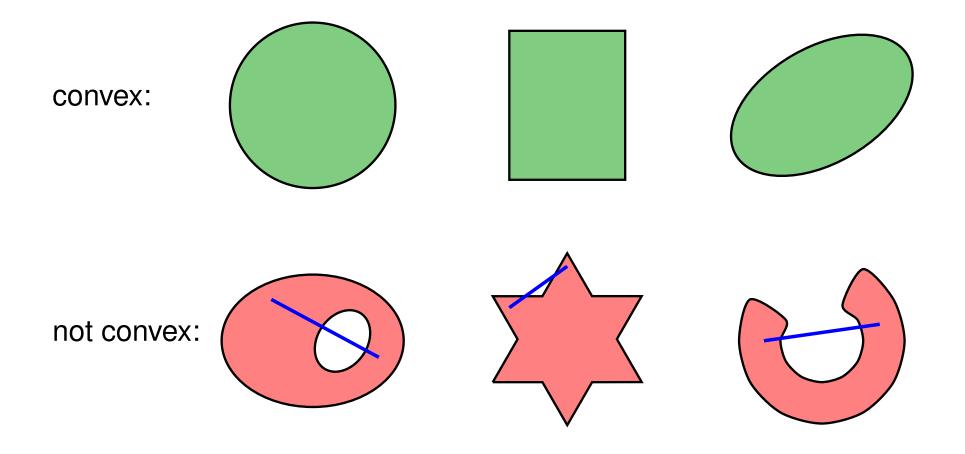
That is, f is one-to-one.

So if f is onto and strictly monotonically increasing (or decreasing), then f is **invertible**.

### **Convex Set**

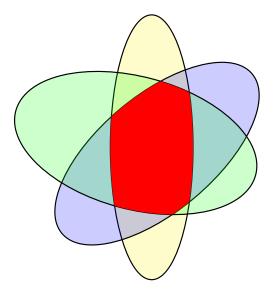
A set  $D \subseteq \mathbb{R}^n$  is called **convex**, if for any two points  $\mathbf{x}, \mathbf{y} \in D$  the straight line segment between these points also belongs to D, i.e.,

 $(1-h) \mathbf{x} + h \mathbf{y} \in D$  for all  $h \in [0,1]$ , and  $\mathbf{x}, \mathbf{y} \in D$ .



# **Intersection of Convex Sets**

Let  $S_1, \ldots, S_k$  be convex subsets of  $\mathbb{R}^n$ . Then their *intersection*  $S_1 \cap \ldots \cap S_k$  is also convex.



The union of convex sets need not be convex.

### **Example – Half-Space**

Let  $\mathbf{p} \in \mathbb{R}^n$  and  $m \in \mathbb{R}$  be fixed,  $\mathbf{p} \neq 0$ . Then

$$H = \{ \mathbf{x} \in \mathbb{R}^n \colon \mathbf{p}^\mathsf{T} \cdot \mathbf{x} = m \}$$

is a so called **hyper-plane** which partitions the  $\mathbb{R}^n$  into two **half-spaces** 

$$H_{+} = \{ \mathbf{x} \in \mathbb{R}^{n} : \mathbf{p}^{\mathsf{T}} \cdot \mathbf{x} \ge m \} ,$$
  
$$H_{-} = \{ \mathbf{x} \in \mathbb{R}^{n} : \mathbf{p}^{\mathsf{T}} \cdot \mathbf{x} \le m \} .$$

Sets H,  $H_+$  and  $H_-$  are convex.

Let x be a vector of goods, p the vector of prices and m the budget. Then the budget set is convex.

$$\{\mathbf{x} \in \mathbb{R}^n \colon \mathbf{p}^\mathsf{T} \cdot \mathbf{x} \le m, \mathbf{x} \ge 0\}$$
  
=  $\{\mathbf{x} \colon \mathbf{p}^\mathsf{T} \cdot \mathbf{x} \le m\} \cap \{\mathbf{x} \colon x_1 \ge 0\} \cap \ldots \cap \{\mathbf{x} \colon x_n \ge 0\}$ 

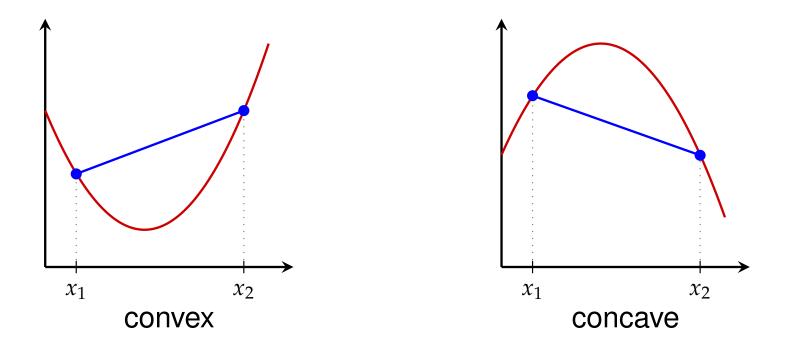
### **Convex and Concave Functions**

Function *f* is called **convex** in domain  $D \subseteq \mathbb{R}^n$ , if *D* is *convex* and

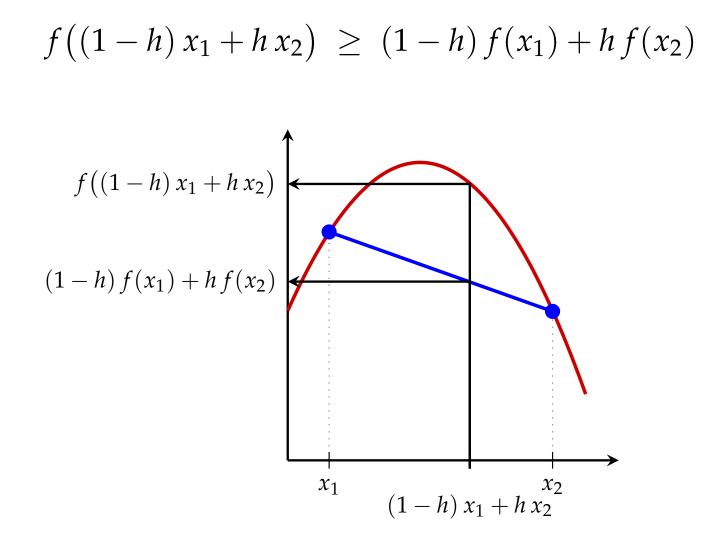
$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) \le (1-h)f(\mathbf{x}_1) + hf(\mathbf{x}_2)$$

for all  $\mathbf{x}_1, \mathbf{x}_2 \in D$  and all  $h \in [0, 1]$ . It is called **concave**, if

 $f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) \ge (1-h)f(\mathbf{x}_1) + hf(\mathbf{x}_2)$ 



#### **Concave Function**\*



Secant is below the graph of function f.

# **Strictly Convex and Concave Functions**

Function *f* is **strictly convex** in domain  $D \subseteq \mathbb{R}^n$ , if *D* is *convex* and

$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) < (1-h)f(\mathbf{x}_1) + hf(\mathbf{x}_2)$$

for all  $\mathbf{x}_1, \mathbf{x}_2 \in D$  with  $\mathbf{x}_1 \neq \mathbf{x}_2$  and all  $h \in (0, 1)$ .

Function *f* is **strictly concave** in domain  $D \subseteq \mathbb{R}^n$ , if *D* is *convex* and

$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) > (1-h)f(\mathbf{x}_1) + hf(\mathbf{x}_2)$$

for all  $\mathbf{x}_1, \mathbf{x}_2 \in D$  with  $\mathbf{x}_1 \neq \mathbf{x}_2$  and all  $h \in (0, 1)$ .

### **Example – Linear Function**

Let  $\mathbf{a} \in \mathbb{R}^n$  be fixed. Then  $f(\mathbf{x}) = \mathbf{a}^T \cdot \mathbf{x}$  is a linear map and we find:  $f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) = \mathbf{a}^T \cdot ((1-h)\mathbf{x}_1 + h\mathbf{x}_2)$   $= (1-h)\mathbf{a}^T \cdot \mathbf{x}_1 + h\mathbf{a}^T \cdot \mathbf{x}_2$  $= (1-h)f(\mathbf{x}_1) + hf(\mathbf{x}_2)$ 

That is, every *linear function* is both *concave and convex*.

However, a linear function is neither strictly concave nor strictly convex, as the inequality is never strict.

### **Example – Quadratic Univariate Function**

Function 
$$f(x) = x^2$$
 is strictly convex:  

$$\begin{aligned} f((1-h)x + hy) - \left[(1-h)f(x) + hf(y)\right] \\ &= ((1-h)x + hy)^2 - \left[(1-h)x^2 + hy^2\right] \\ &= (1-h)^2 x^2 + 2(1-h)hxy + h^2 y^2 - (1-h)x^2 - hy^2 \\ &= -h(1-h)x^2 + 2(1-h)hxy - h(1-h)y^2 \\ &= -h(1-h)(x-y)^2 \\ &< 0 \quad \text{for } x \neq y \text{ and } 0 < h < 1. \end{aligned}$$

Thus

$$f((1-h)x + hy) < (1-h)f(x) + hf(y)$$

for all  $x \neq y$  and 0 < h < 1, i.e.,  $f(x) = x^2$  is strictly convex, as claimed.

# **Properties**

- ► If f(x) is (strictly) convex, then -f(x) is (strictly) concave (and vice versa).
- If  $f_1(\mathbf{x}), \ldots, f_k(\mathbf{x})$  are *convex* (concave) functions and  $\alpha_1, \ldots, \alpha_k > 0$ , then

$$g(\mathbf{x}) = \alpha_1 f_1(\mathbf{x}) + \cdots + \alpha_k f_k(\mathbf{x})$$

is also *convex* (concave).

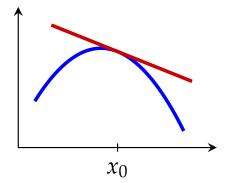
► If (at least) one of the functions  $f_i(x)$  is *strictly convex* (strictly concave), then g(x) is strictly convex (strictly concave).

# **Properties**

For a differentiable functions the following holds:

► Function *f* is **concave** if and only if

$$f(\mathbf{x}) - f(\mathbf{x}_0) \le \nabla f(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0)$$



i.e., the function graph is always below the tangent.

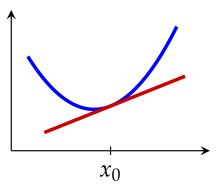
► Function *f* is **strictly concave** if and only if

$$f(\mathbf{x}) - f(\mathbf{x}_0) < \nabla f(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0) \quad \text{for all } \mathbf{x} \neq \mathbf{x}_0$$

Function f is convex if and only if

$$f(\mathbf{x}) - f(\mathbf{x}_0) \ge \nabla f(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0)$$

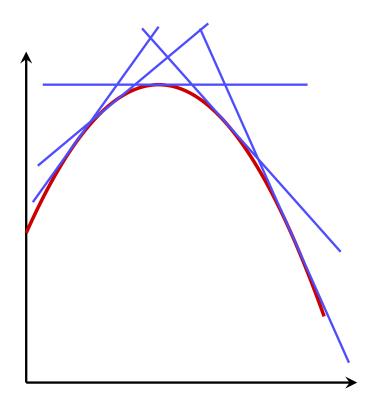
(Analogous for strictly convex functions.)



# **Univariate Functions**\*

For two times differentiable functions we have

$$\begin{array}{ll} f \ {\rm convex} & \Leftrightarrow & f''(x) \geq 0 & \ {\rm for \ all} \ x \in D_f \\ f \ {\rm concave} & \Leftrightarrow & f''(x) \leq 0 & \ {\rm for \ all} \ x \in D_f \end{array}$$



Derivative f'(x) is monotonically decreasing,

thus  $f''(x) \leq 0$ .

# **Univariate Functions**\*

For two times differentiable functions we have

f strictly convex  $\Leftarrow f''(x) > 0$  for all  $x \in D_f$ f strictly concave  $\Leftarrow f''(x) < 0$  for all  $x \in D_f$ 

# **Example – Convex Function\***

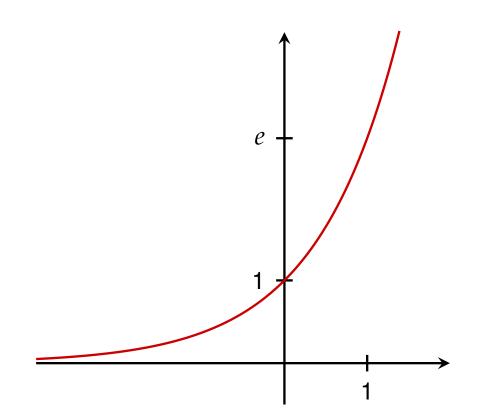
Exponential function:

$$f(x) = e^{x}$$
  

$$f'(x) = e^{x}$$
  

$$f''(x) = e^{x} > 0 \text{ for all } x \in \mathbb{R}$$

exp(x) is (strictly) convex.



# **Example – Concave Function\***

Logarithm function: (x > 0)  $f(x) = \ln(x)$   $f'(x) = \frac{1}{x}$   $f''(x) = -\frac{1}{x^2} < 0$  for all x > 0 $\ln(x)$  is (strictly) concave.

# **Locally Convex Functions**\*

A function f can be convex in some interval and concave in some other interval.

For two times *continuously* differentiable functions (i.e., when f''(x) is continuous) we can use the following procedure:

- **1.** Compute second derivative f''(x).
- **2.** Determine all roots of f''(x).
- **3.** We thus obtain intervals where f''(x) does not change sign.
- **4.** Select appropriate points  $x_i$  in each interval and determine the sign of  $f''(x_i)$ .

# **Locally Concave Function\***

In which region is  $f(x) = 2 x^3 - 12 x^2 + 18 x - 1$  concave?

We have to solve inequality  $f''(x) \leq 0$ .

**1.** 
$$f''(x) = 12x - 24$$

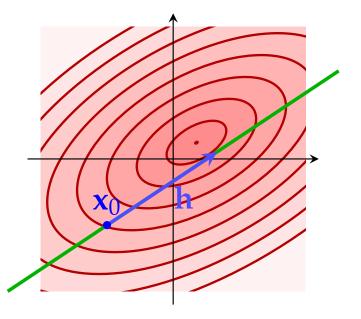
- **2.** Roots:  $12x 24 = 0 \implies x = 2$
- **3.** Obtain 2 intervals:  $(-\infty, 2]$  and  $[2, \infty)$
- 4. Sign of f''(x) at appropriate points in each interval: f''(0) = -24 < 0 and f''(4) = 24 > 0.

**5.** f''(x) cannot change sign in each interval:  $f''(x) \le 0$  in  $(-\infty, 2]$ Function f(x) is concave in  $(-\infty, 2]$ .

# **Univariate Restrictions**

Notice, that by definition a (multivariate) function is convex if and only if every restriction of its domain to a straight line results in a convex univariate function. That is:

Function  $f: D \subset \mathbb{R}^n \to \mathbb{R}$  is convex if and only if  $g(t) = f(\mathbf{x}_0 + t \cdot \mathbf{h})$  is convex for all  $\mathbf{x}_0 \in D$  and all non-zero  $\mathbf{h} \in \mathbb{R}^n$ .



# **Quadratic Form**

Let  ${\bf A}$  be a symmetric matrix

and  $q_{\mathbf{A}}(\mathbf{x}) = \mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}$  be the corresponding quadratic form.

Matrix A can be diagonalized, i.e., if we use an orthonormal basis of its eigenvectors, then A becomes a diagonal matrix with the eigenvalues of A as its elements:

$$q_{\mathbf{A}}(\mathbf{x}) = \lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2 .$$

- lt is convex if all eigenvalues  $\lambda_i \ge 0$ as it is the sum of convex functions.
- It is concave if all  $\lambda_i \leq 0$  as it is the negative of a convex function.
- ► It is neither convex nor concave if we have eigenvalues with  $\lambda_i > 0$  and  $\lambda_i < 0$ .

# **Quadratic Form**

We find for a quadratic form  $q_{\mathbf{A}}$ :

- ► strictly convex ⇔ positive definite
- ► convex ⇔ positive semidefinite
- ► strictly concave ⇔ negative definite
- ► concave ⇔ negative semidefinite
- ▶ neither ⇔ indefinite

We can determine the definiteness of  ${\bf A}$  by means of

- ► the eigenvalues of A, or
- ► the (leading) principle minors of A.

### **Example – Quadratic Form**

Let 
$$\mathbf{A} = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 3 & -1 \\ 0 & -1 & 2 \end{pmatrix}$$
. Leading principle minors:  
 $A_1 = 2 > 0$   
 $A_2 = \begin{vmatrix} 2 & 1 \\ 1 & 3 \end{vmatrix} = 5 > 0$   
 $A_3 = |\mathbf{A}| = \begin{vmatrix} 2 & 1 & 0 \\ 1 & 3 & -1 \\ 0 & -1 & 2 \end{vmatrix} = 8 > 0$ 

A is thus positive definite. Quadratic form  $q_A$  is *strictly convex*.

### **Example – Quadratic Form**

Let 
$$\mathbf{A} = \begin{pmatrix} -1 & 0 & 1 \\ 0 & -4 & 2 \\ 1 & 2 & -2 \end{pmatrix}$$
. Principle Minors:

$$A_{1} = -1 \qquad A_{2} = -4 \qquad A_{3} = -2$$

$$A_{1,2} = \begin{vmatrix} -1 & 0 \\ 0 & -4 \end{vmatrix} = 4 \qquad A_{1,3} = \begin{vmatrix} -1 & 1 \\ 1 & -2 \end{vmatrix} = 1 \qquad A_{2,3} = \begin{vmatrix} -4 & 2 \\ 2 & -2 \end{vmatrix} = 4$$

$$A_{1,2,3} = \begin{vmatrix} -1 & 0 & 1 \\ 0 & -4 & 2 \\ 1 & 2 & -2 \end{vmatrix} = 0 \qquad A_{i,j} \leq 0$$

$$A_{1,2,3} \leq 0$$

A is thus negative semidefinite.

Quadratic form  $q_A$  is *concave* (but not strictly concave).

# **Concavity of Differentiable Functions**

Le  $f: D \subseteq \mathbb{R}^n \to \mathbb{R}$  with Taylor series expansion

 $f(\mathbf{x}_0 + \mathbf{h}) = f(\mathbf{x}_0) + \nabla f(\mathbf{x}_0) \cdot \mathbf{h} + \frac{1}{2} \mathbf{h}^{\mathsf{T}} \cdot \mathbf{H}_f(\mathbf{x}_0) \cdot \mathbf{h} + \mathcal{O}(\|\mathbf{h}\|^3)$ 

*Hessian matrix*  $\mathbf{H}_{f}(\mathbf{x}_{0})$  determines the concavity or convexity of f around expansion point  $\mathbf{x}_{0}$ .

► H<sub>f</sub>(x<sub>0</sub>) positive definite ⇒ f strictly convex around x<sub>0</sub>
 ► H<sub>f</sub>(x<sub>0</sub>) negative definite ⇒ f strictly concave around x<sub>0</sub>

► H<sub>f</sub>(x) positive semidefinite for all x ∈ D ⇔ f convex in D
► H<sub>f</sub>(x) negative semidefinite for all x ∈ D ⇔ f concave in D

# **Recipe – Strictly Convex**

**1.** Compute Hessian matrix

$$\mathbf{H}_{f}(\mathbf{x}) = \begin{pmatrix} f_{x_{1}x_{1}}(\mathbf{x}) & f_{x_{1}x_{2}}(\mathbf{x}) & \cdots & f_{x_{1}x_{n}}(\mathbf{x}) \\ f_{x_{2}x_{1}}(\mathbf{x}) & f_{x_{2}x_{2}}(\mathbf{x}) & \cdots & f_{x_{2}x_{n}}(\mathbf{x}) \\ \vdots & \vdots & \ddots & \vdots \\ f_{x_{n}x_{1}}(\mathbf{x}) & f_{x_{n}x_{2}}(\mathbf{x}) & \cdots & f_{x_{n}x_{n}}(\mathbf{x}) \end{pmatrix}$$

**2.** Compute all *leading principle minors*  $H_i$ .

3.

*f strictly convex* ⇔ all *H<sub>k</sub>* > 0 for (almost) **all** *x* ∈ *D f strictly concave* ⇔ all (−1)<sup>k</sup>*H<sub>k</sub>* > 0 for (almost) **all** *x* ∈ *D*

 $[(-1)^k H_k > 0 \text{ implies: } H_1, H_3, \ldots < 0 \text{ and } H_2, H_4, \ldots > 0]$ 

**4.** Otherwise *f* is *neither* **strictly** convex *nor* strictly concave.

# **Recipe – Convex**

**1.** Compute Hessian matrix

$$\mathbf{H}_{f}(\mathbf{x}) = \begin{pmatrix} f_{x_{1}x_{1}}(\mathbf{x}) & f_{x_{1}x_{2}}(\mathbf{x}) & \cdots & f_{x_{1}x_{n}}(\mathbf{x}) \\ f_{x_{2}x_{1}}(\mathbf{x}) & f_{x_{2}x_{2}}(\mathbf{x}) & \cdots & f_{x_{2}x_{n}}(\mathbf{x}) \\ \vdots & \vdots & \ddots & \vdots \\ f_{x_{n}x_{1}}(\mathbf{x}) & f_{x_{n}x_{2}}(\mathbf{x}) & \cdots & f_{x_{n}x_{n}}(\mathbf{x}) \end{pmatrix}$$

**2.** Compute all *principle minors*  $H_{i_1,...,i_k}$ . (Only required if det( $\mathbf{H}_f$ ) = 0, see below)

**3.** ► *f* convex 
$$\Leftrightarrow$$
 all  $H_{i_1,...,i_k} \ge 0$  for all  $\mathbf{x} \in D$ .  
► *f* concave  $\Leftrightarrow$  all  $(-1)^k H_{i_1,...,i_k} \ge 0$  for all  $\mathbf{x} \in D$ .

**4.** Otherwise f is *neither* convex *nor* concave.

# **Recipe – Convex II**

Computation of *all* principle minors can be avoided if  $det(\mathbf{H}_f) \neq 0$ . Then a function is either strictly convex/concave (and thus convex/concave) or neither convex nor concave.

In particular we have the following recipe:

- **1.** Compute Hessian matrix  $\mathbf{H}_{f}(\mathbf{x})$ .
- **2.** Compute all *leading principle minors*  $H_i$ .
- **3.** Check if  $det(\mathbf{H}_f) \neq 0$ .
- 4. Check for strict convexity or concavity.
- **5.** If  $det(\mathbf{H}_f) \neq 0$  and f is neither strictly convex nor concave, then f is neither convex nor concave, either.

# **Example – Strict Convexity**

Is function f (strictly) concave or convex?

$$f(x,y) = x^4 + x^2 - 2xy + y^2$$

**1.** Hessian matrix: 
$$\mathbf{H}_{f}(\mathbf{x}) = \begin{pmatrix} 12 \, x^{2} + 2 & -2 \\ -2 & 2 \end{pmatrix}$$

2. Leading principle minors:  $H_1 = 12 x^2 + 2$  > 0  $H_2 = |\mathbf{H}_f(\mathbf{x})| = 24 x^2$  > 0 for all  $x \neq 0$ .

**3.** All leading principle minors > 0 for almost all  $\mathbf{x}$  $\Rightarrow f$  is *strictly convex*. (and thus convex, too)

### **Example – Cobb-Douglas Function**

Let 
$$f(x, y) = x^{\alpha}y^{\beta}$$
 with  $\alpha, \beta \ge 0$  and  $\alpha + \beta \le 1$ ,  
and  $D = \{(x, y) : x, y \ge 0\}.$ 

Hessian matrix at **x**:

$$\mathbf{H}_{f}(\mathbf{x}) = \begin{pmatrix} \alpha(\alpha-1) \, x^{\alpha-2} y^{\beta} & \alpha\beta \, x^{\alpha-1} y^{\beta-1} \\ \alpha\beta \, x^{\alpha-1} y^{\beta-1} & \beta(\beta-1) \, x^{\alpha} y^{\beta-2} \end{pmatrix}$$

Principle Minors:

$$H_{1} = \underbrace{\alpha}_{\geq 0} \underbrace{(\alpha - 1)}_{\leq 0} \underbrace{x^{\alpha - 2} y^{\beta}}_{\geq 0} \leq 0$$
$$H_{2} = \underbrace{\beta}_{\geq 0} \underbrace{(\beta - 1)}_{\leq 0} \underbrace{x^{\alpha} y^{\beta - 2}}_{\geq 0} \leq 0$$

### **Example – Cobb-Douglas Function**

$$\begin{split} H_{1,2} &= |\mathbf{H}_{f}(\mathbf{x})| \\ &= \alpha(\alpha-1) \, x^{\alpha-2} y^{\beta} \cdot \beta(\beta-1) \, x^{\alpha} y^{\beta-2} - (\alpha \beta \, x^{\alpha-1} y^{\beta-1})^{2} \\ &= \alpha(\alpha-1) \, \beta(\beta-1) \, x^{2\alpha-2} y^{2\beta-2} - \alpha^{2} \beta^{2} \, x^{2\alpha-2} y^{2\beta-2} \\ &= \alpha \beta [(\alpha-1)(\beta-1) - \alpha \beta] x^{2\alpha-2} y^{2\beta-2} \\ &= \underbrace{\alpha \beta}_{\geq 0} \underbrace{(1-\alpha-\beta)}_{\geq 0} \underbrace{x^{2\alpha-2} y^{2\beta-2}}_{\geq 0} \quad \ge 0 \end{split}$$

 $H_1 \leq 0$  and  $H_2 \leq 0$ , and  $H_{1,2} \geq 0$  for all  $(x, y) \in D$ . f(x, y) thus is *concave* in *D*.

For  $0 < \alpha, \beta < 1$  and  $\alpha + \beta < 1$  we even find:  $H_1 = H_1 < 0$  and  $H_2 = |\mathbf{H}_f(\mathbf{x})| > 0$  for almost all  $(x, y) \in D$ . f(x, y) is then *strictly concave*.

# **Lower Level Sets of Convex Functions**

Assume that f is *convex*. Then the **lower level sets** of f

$$\{\mathbf{x}\in D_f\colon f(\mathbf{x})\leq c\}$$

are convex.

Let 
$$\mathbf{x}_1, \mathbf{x}_2 \in {\mathbf{x} \in D_f : f(\mathbf{x}) \le c}$$
,  
i.e.,  $f(\mathbf{x}_1), f(\mathbf{x}_2) \le c$ .

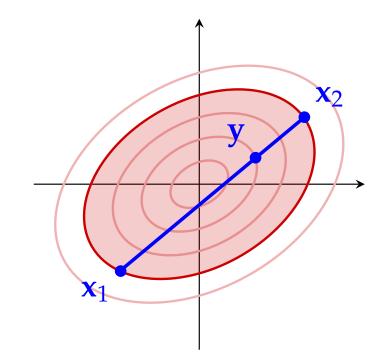
Then for 
$$\mathbf{y} = (1 - h)\mathbf{x}_1 + h\mathbf{x}_2$$
  
where  $h \in [0, 1]$  we find

$$f(\mathbf{y}) = f((1-h)\mathbf{x}_1 + h\mathbf{x}_2)$$
  

$$\leq (1-h) f(\mathbf{x}_1) + h f(\mathbf{x}_2)$$
  

$$\leq (1-h)c + hc = c$$

That is,  $\mathbf{y} \in {\mathbf{x} \in D_f : f(\mathbf{x}) \le c}$ , too.

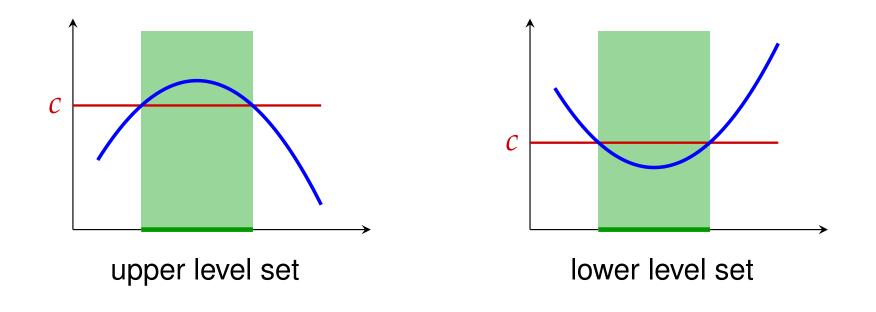


# **Upper Level Sets of Concave Functions**

Assume that f is *concave*. Then the **upper level sets** of f

 $\{\mathbf{x} \in D_f \colon f(\mathbf{x}) \ge c\}$ 

are convex.



# **Extremum and Monotone Transformation**

Let  $T \colon \mathbb{R} \to \mathbb{R}$  be a *strictly monotonically increasing* function.

If  $\mathbf{x}^*$  is a *maximum* of f, then  $\mathbf{x}^*$  is also a maximum of  $T \circ f$ .

As  $\mathbf{x}^*$  is a *maximum* of f, we have

 $f(\mathbf{x}^*) \ge f(\mathbf{x})$  for all  $\mathbf{x}$ .

As T is strictly monotonically increasing, we have

 $T(x_1) > T(x_2)$  falls  $x_1 > x_2$ .

Thus we find

 $(T \circ f)(\mathbf{x}^*) = T(f(\mathbf{x}^*)) > T(f(\mathbf{x})) = (T \circ f)(\mathbf{x})$  for all  $\mathbf{x}$ ,

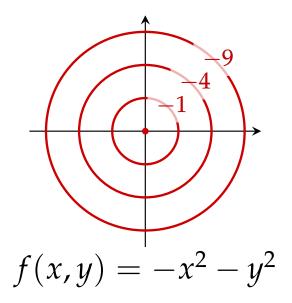
i.e.,  $\mathbf{x}^*$  is a maximum of  $T \circ f$ .

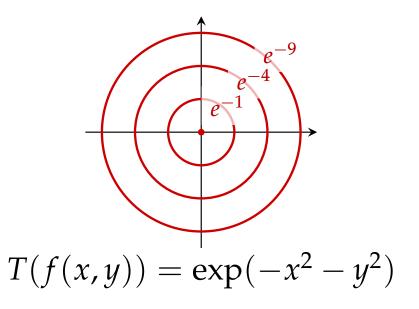
As *T* is one-to-one we also get the converse statement: If  $\mathbf{x}^*$  is a *maximum* of  $T \circ f$ , then it also is a maximum of *f*.

# **Extremum and Monotone Transformation**

A strictly monotonically increasing Transformation T preserves the extrema of f.

Transformation T also preserves the level sets of f:





# **Quasi-Convex and Quasi-Concave**

Function *f* is called **quasi-convex** in  $D \subseteq \mathbb{R}^n$ , if *D* is *convex* and every *lower level set*  $\{\mathbf{x} \in D_f : f(\mathbf{x}) \leq c\}$  is *convex*.

Function f is called **quasi-concave** in  $D \subseteq \mathbb{R}^n$ , if D is *convex* and every *upper level set*  $\{\mathbf{x} \in D_f : f(\mathbf{x}) \ge c\}$  is *convex*.

## **Convex and Quasi-Convex**

Every *concave* (convex) function also is *quasi-concave* (and quasi-convex, resp.).

However, a quasi-concave function need not be concave.

Let *T* be a strictly monotonically increasing function. If function  $f(\mathbf{x})$  is *concave* (convex), then  $T \circ f$  is *quasi-concave* (and quasi-convex, resp.).

Function  $g(x, y) = e^{-x^2 - y^2}$  is quasi-concave, as  $f(x, y) = -x^2 - y^2$  is concave and  $T(x) = e^x$  is strictly monotonically increasing. However,  $g = T \circ f$  is not concave.

# A Weaker Condition

The notion of *quasi-convex* is **weaker** than that of *convex* in the sense that every convex function also is quasi-convex but not vice versa. There are much more quasi-convex functions than convex ones.

The importance of such a weaker notions is based on the observation that a couple of propositions still hold if "convex" is replaced by "quasi-convex".

In this way we get a generalization of a theorem, where a *stronger* condition is replaced by a *weaker* one.

# **Quasi-Convex and Quasi-Concave II**

Function f is quasi-convex if and only if

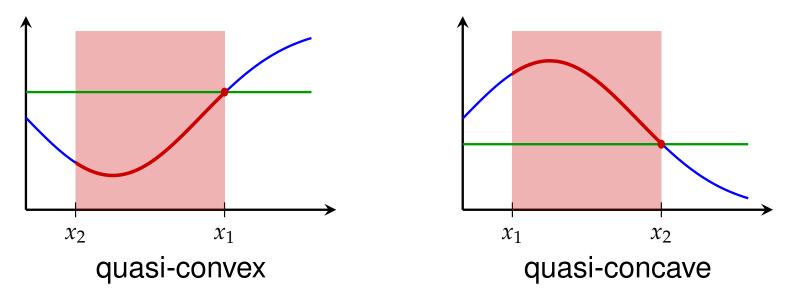
$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) \le \max\{f(\mathbf{x}_1), f(\mathbf{x}_2)\}$$

for all  $\mathbf{x}_1, \mathbf{x}_2$  and  $h \in [0, 1]$ .

Function f is quasi-concave if and only if

 $f((1-h)\mathbf{x}_1+h\mathbf{x}_2) \geq \min\{f(\mathbf{x}_1), f(\mathbf{x}_2)\}$ 

for all  $\mathbf{x}_1, \mathbf{x}_2$  and  $h \in [0, 1]$ .



# **Strictly Quasi-Convex and Quasi-Concave**

► Function *f* is called **strictly quasi-convex** if

$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) < \max\{f(\mathbf{x}_1), f(\mathbf{x}_2)\}\$$

for all  $\mathbf{x}_1, \mathbf{x}_2$ , with  $\mathbf{x}_1 \neq \mathbf{x}_2$ , and  $h \in (0, 1)$ .

Function f is called strictly quasi-concave if

$$f((1-h)\mathbf{x}_1 + h\mathbf{x}_2) > \min\{f(\mathbf{x}_1), f(\mathbf{x}_2)\}$$

for all  $\mathbf{x}_1, \mathbf{x}_2$ , with  $\mathbf{x}_1 \neq \mathbf{x}_2$ , and  $h \in (0, 1)$ .

# **Quasi-convex and Quasi-Concave III**

For a differentiable function f we find:

► Function *f* is *quasi-convex* if and only if

$$f(\mathbf{x}) \leq f(\mathbf{x}_0) \quad \Rightarrow \quad \nabla f(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0) \leq 0$$

► Function *f* is *quasi-concave* if and only if

$$f(\mathbf{x}) \ge f(\mathbf{x}_0) \quad \Rightarrow \quad \nabla f(\mathbf{x}_0) \cdot (\mathbf{x} - \mathbf{x}_0) \ge 0$$

# Summary

- monotone function
- convex set
- convex and concave function
- convexity and definiteness of quadratic form
- minors of Hessian matrix
- quasi-convex and quasi-concave function