

**Matrix Algebra**

$$\begin{aligned} [\alpha \mathbf{A}]_{ij} &= \alpha [\mathbf{A}]_{ij} \\ [\mathbf{A} + \mathbf{B}]_{ij} &= [\mathbf{A}]_{ij} + [\mathbf{B}]_{ij} \\ [\mathbf{A} \cdot \mathbf{B}]_{ij} &= \sum_{s=1}^n [\mathbf{A}]_{is} [\mathbf{B}]_{sj} \\ \|\mathbf{x}\| &= \sqrt{\mathbf{x}^t \mathbf{x}} \end{aligned}$$

**Determinant**

$$\mathbf{A}^{-1} = \frac{1}{|\mathbf{A}|} \mathbf{A}^{*t}$$

**Eigenvalues**

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{A}$$

$$A_k = \begin{vmatrix} a_{11} & \dots & a_{1k} \\ \vdots & \ddots & \vdots \\ a_{k1} & \dots & a_{kk} \end{vmatrix}$$

$$A_{i_1, \dots, i_k} = \begin{vmatrix} a_{i_1, i_1} & \dots & a_{i_1, i_k} \\ \vdots & \ddots & \vdots \\ a_{i_k, i_1} & \dots & a_{i_k, i_k} \end{vmatrix}$$

$\mathbf{A}$  positive definite  $\Leftrightarrow$  all  $\lambda_k > 0 \Leftrightarrow$  all  $A_k > 0$

**Limits**

$$\lim_{n \rightarrow \infty} \left(1 + \frac{1}{n}\right)^n = e$$

$$\begin{aligned} \lim_{x \rightarrow x_0} \frac{f(x)}{g(x)} &= \lim_{x \rightarrow x_0} \frac{f'(x)}{g'(x)} \\ \text{if } \lim_{x \rightarrow x_0} f(x) &= \lim_{x \rightarrow x_0} g(x) = 0 \ (\neq \infty) \end{aligned}$$

**Derivatives**

$$(x^\alpha)' = \alpha \cdot x^{\alpha-1}$$

$$(e^x)' = e^x$$

$$(\ln(x))' = \frac{1}{x}$$

$$(\sin(x))' = \cos(x)$$

$$(\cos(x))' = -\sin(x)$$

$$(f(x) \cdot g(x))' = f'(x) \cdot g(x) + f(x) \cdot g'(x)$$

$$(f(g(x)))' = f'(g(x)) \cdot g'(x)$$

$$\varepsilon_f(x) = x \cdot \frac{f'(x)}{f(x)}$$

**Multivariate Analysis**

gradient:  $\nabla f(\mathbf{x}) = (f_{x_1}(\mathbf{x}), \dots, f_{x_n}(\mathbf{x}))$

directional derivative:  $\frac{\partial f}{\partial \mathbf{h}} = \nabla f(\mathbf{x}) \cdot \mathbf{h}$  ,  $\|\mathbf{h}\| = 1$

Jacobian Matrix:

$$f'(\mathbf{x}) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(\mathbf{x}) & \dots & \frac{\partial f_1}{\partial x_n}(\mathbf{x}) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1}(\mathbf{x}) & \dots & \frac{\partial f_m}{\partial x_n}(\mathbf{x}) \end{pmatrix}$$

$$(g \circ f)'(\mathbf{x}) = g'(f(\mathbf{x})) \cdot f'(\mathbf{x})$$

Hessian matrix:

$$\mathbf{H}_f(\mathbf{x}) = \begin{pmatrix} f_{x_1 x_1}(\mathbf{x}) & \dots & f_{x_1 x_n}(\mathbf{x}) \\ \vdots & \ddots & \vdots \\ f_{x_n x_1}(\mathbf{x}) & \dots & f_{x_n x_n}(\mathbf{x}) \end{pmatrix}$$

**Inverse and Implicit Functions**

$$(f^{-1})'(\mathbf{y}) = (f'(\mathbf{x}))^{-1} \ , \ \mathbf{y} = f(\mathbf{x})$$

Derivative of implicit function  $\mathbf{F}(x_1, \dots, x_n) = 0$ :

$$\frac{\partial x_i}{\partial x_k} = -\frac{F_{x_k}}{F_{x_i}}$$

**Taylor Series**

$$f(x) \approx f(0) + \frac{f'(0)}{1!} x + \frac{f''(0)}{2!} x^2 + \dots + \frac{f^{(n)}(0)}{n!} x^n$$

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + R_n(x)$$

Important Taylor series:

$$\exp(x) = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$

$$\ln(x+1) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$$

$$\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$

$$\cos(x) = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \dots$$

$$f(\mathbf{x}) \approx f(\mathbf{0}) + \nabla f(\mathbf{0})^t \mathbf{x} + \frac{1}{2} \mathbf{x}^t \mathbf{H}_f(\mathbf{0}) \mathbf{x}$$

$$f(\mathbf{x}) \approx f(\mathbf{x}_0) + \nabla f(\mathbf{x}_0)^t (\mathbf{x} - \mathbf{x}_0) + \frac{1}{2} (\mathbf{x} - \mathbf{x}_0)^t \mathbf{H}_f(\mathbf{0}) (\mathbf{x} - \mathbf{x}_0)$$

**Integration**

$$\int x^a dx = \frac{1}{a+1} \cdot x^{a+1} + c$$

$$\int e^x dx = e^x + c$$

$$\int \frac{1}{x} dx = \ln|x| + c$$

$$\int \cos(x) dx = \sin(x) + c$$

$$\int \sin(x) dx = -\cos(x) + c$$

$$\int f(x) \cdot g'(x) dx = f(x) \cdot g(x) - \int f'(x) \cdot g(x) dx$$

$$\int f(g(x)) \cdot g'(x) dx = \int f(z) dz \text{ with } z = g(x)$$

**Optimization**

Lagrange function:

$$\mathcal{L}(x, y; \lambda) = f(x, y) + \lambda(c - g(x, y))$$

bordered Hessian:

$$\bar{\mathbf{H}}(\mathbf{x}) = \begin{pmatrix} 0 & g_x & g_y \\ g_x & \mathcal{L}_{xx} & \mathcal{L}_{xy} \\ g_y & \mathcal{L}_{yx} & \mathcal{L}_{yy} \end{pmatrix}$$

$|\bar{\mathbf{H}}(\mathbf{x})| > 0 \Rightarrow \mathbf{x}$  is local maximum

Kuhn-Tucker conditions:

$$\mathcal{L}_{x_j} \leq 0, \quad x_j \geq 0, \quad x_j \mathcal{L}_{x_j} = 0$$

$$\mathcal{L}_{\lambda_i} \geq 0, \quad \lambda_i \geq 0, \quad \lambda_i \mathcal{L}_{\lambda_i} = 0$$